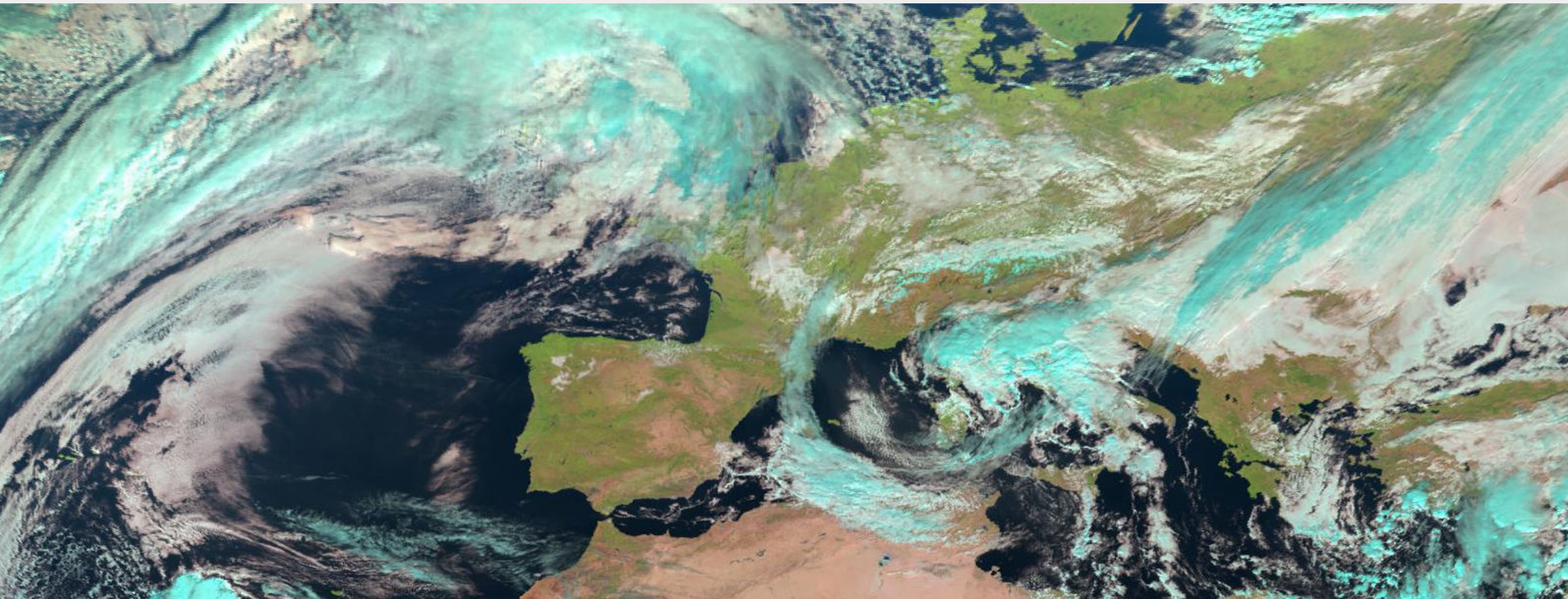


Neural network-based methods for simulating cloud- and aerosol-affected solar satellite channels

Leonhard Scheck^{1,2}, Florian Baur^{1,2}, Olaf Stiller², Christina Stumpf², Christina Köpken-Watts²

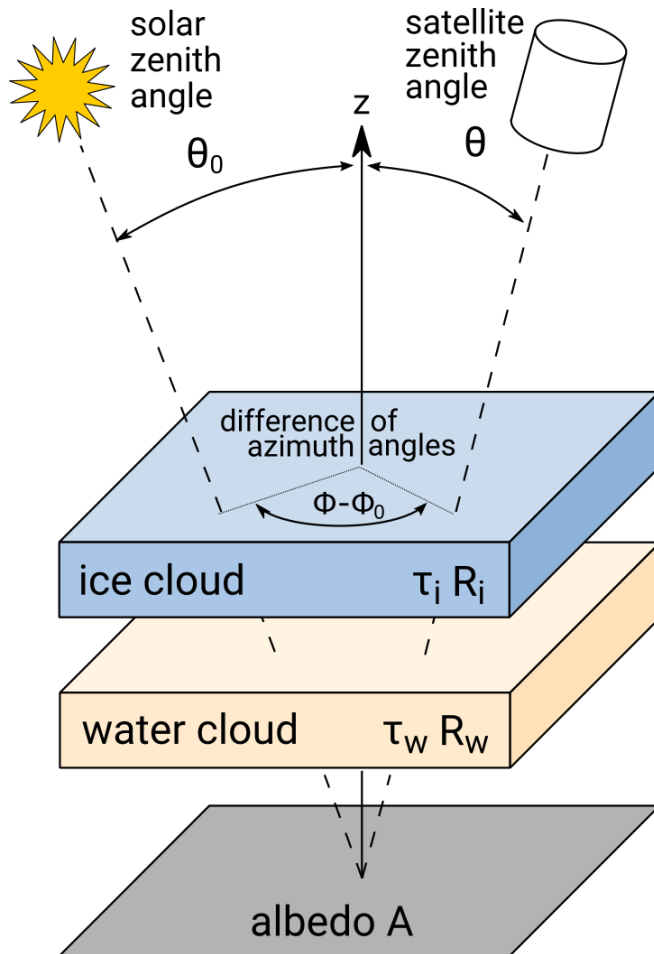
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2) Deutscher Wetterdienst, Offenbach, Germany



MFASIS for cloud-affected visible channels (LUT-based)

Method for Fast Satellite Image Synthesis



The “conventional” (no machine learning) method that has been used for model evaluation + assimilation experiments.

- **Simplify vertical cloud structure:** Complex structure can be replaced by two homogeneous clouds with same optical depth without changing reflectance significantly → only 4 parameters (optical depth, particle size) + 3 angles, albedo → **8 parameters per column**
- **Compute 8-dimensional reflectance look-up table (LUT)** with discrete ordinate method (DOM) for all parameter combinations → **8GB**, use **lossy compression** → **21MB** = O(CPU cache)
- Determine parameters from profile, interpolate in LUT

fast ($O(\mu\text{sec/column})$), mean reflectance error < 0.01
Implem. in RTTOV 12.2 by DWD in collab. with MetOffice

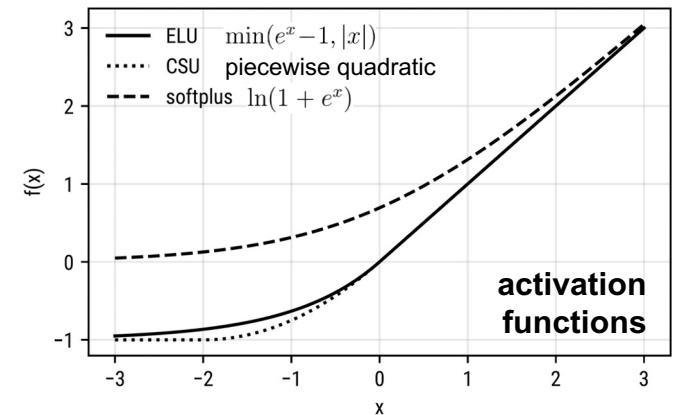
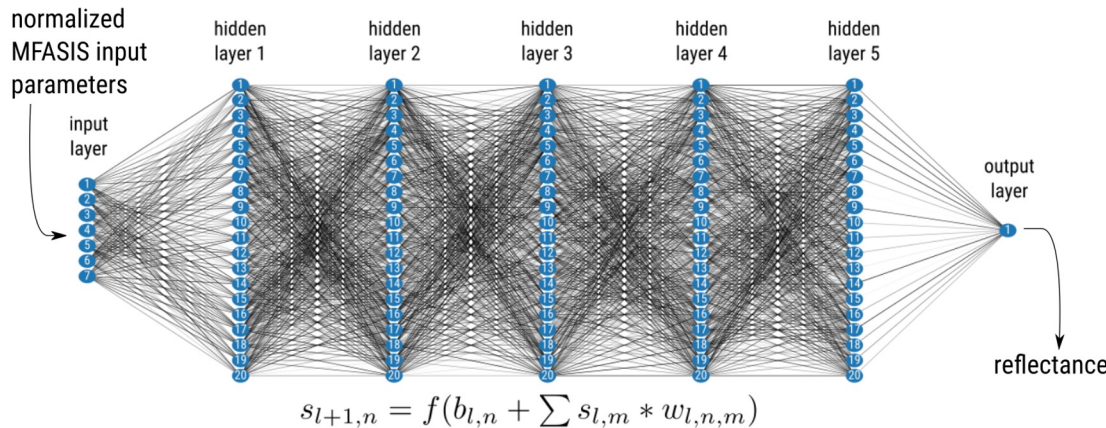
- Simple corrections for mixed-phase clouds and weakly water vapor sensitive channels ($0.8\mu\text{m}$ SEVIRI)
- Preliminary correction for $1.6\mu\text{m}$ channels

Could we replace the LUT by a neural network (NN)?

Motivation: Absorbing channels (water vapor, trace gases, clouds) and aerosols (many different species) require additional input variables → LUT size would explode...

Approach: Keep idealized profile strategy (low number of input parameters) but use relatively small (= fast) feed-forward neural network (several 1000 params.) instead of LUT

First goal: Replace LUT by NN for the visible 0.6μm channel (no additional inputs)



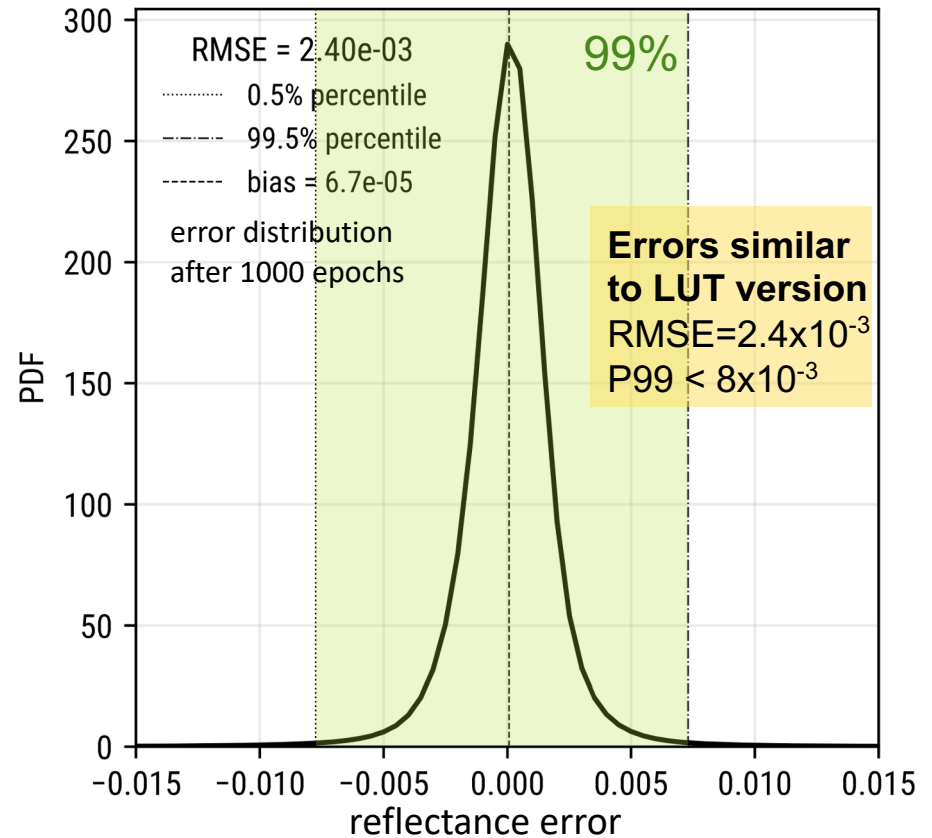
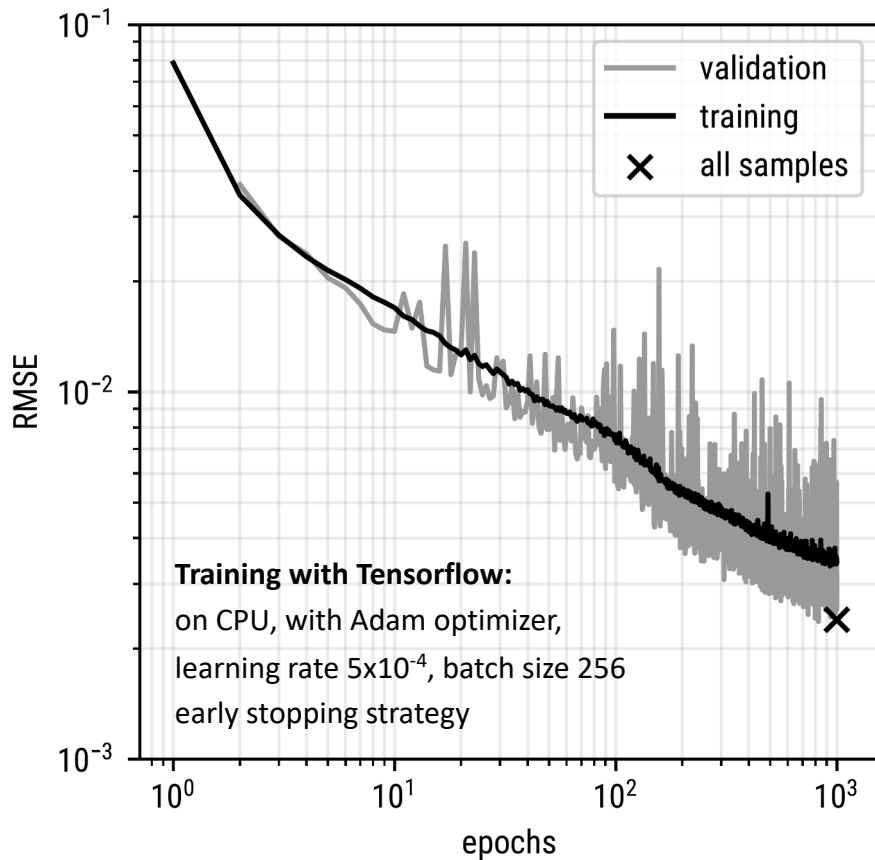
NN structure: best results for 4 – 8 hidden layers (“deep”), CSU activation function

Training data: Synthetic (random numbers for input params., reflectance computed with DOM)
→ produce as much data as is required, cover full parameter space with constant density

Training process: Tensorflow standard methods (Adam optimizer, early stopping strategy)

Error evolution during training for an example

3000 parameters, 6 hidden layers, 23 nodes/layer, 3.4×10^6 samples, trained for 13h



DOM-generated training data can be several 100 times smaller than DOM-generated LUT

Performance

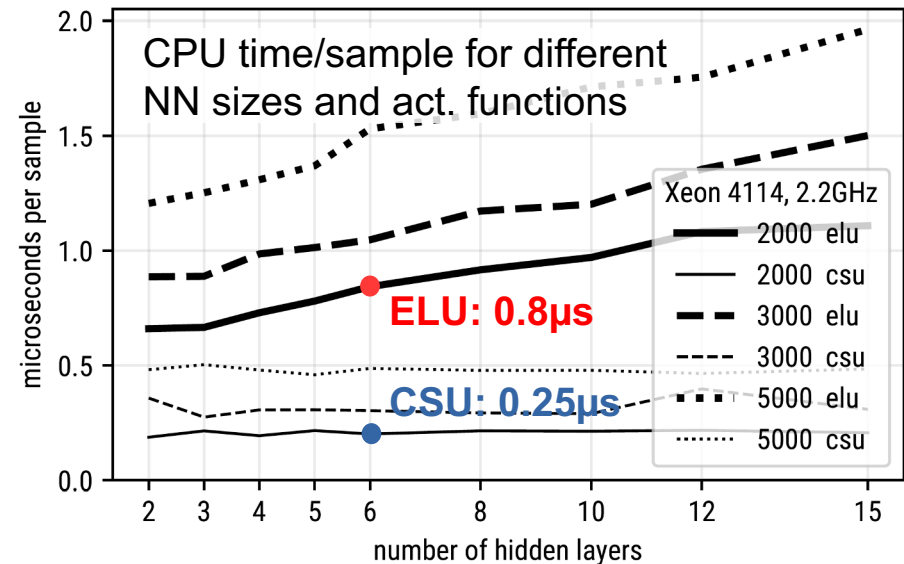
- Development of **Fortran inference code optimized for small NNs** (<100 nodes/layer) (vectorized, much faster than Tensorflow)
- Using a **activation function without exp()** (CSU, piecewise linear/quadratic)
→ inference 3-4 times faster for small NNs

→ **Final version for SEVIRI 0.6 μ m channel 11 x faster than MFASIS-LUT, similar errors**

(and MFASIS-LUT is ~200 x faster than DOM)

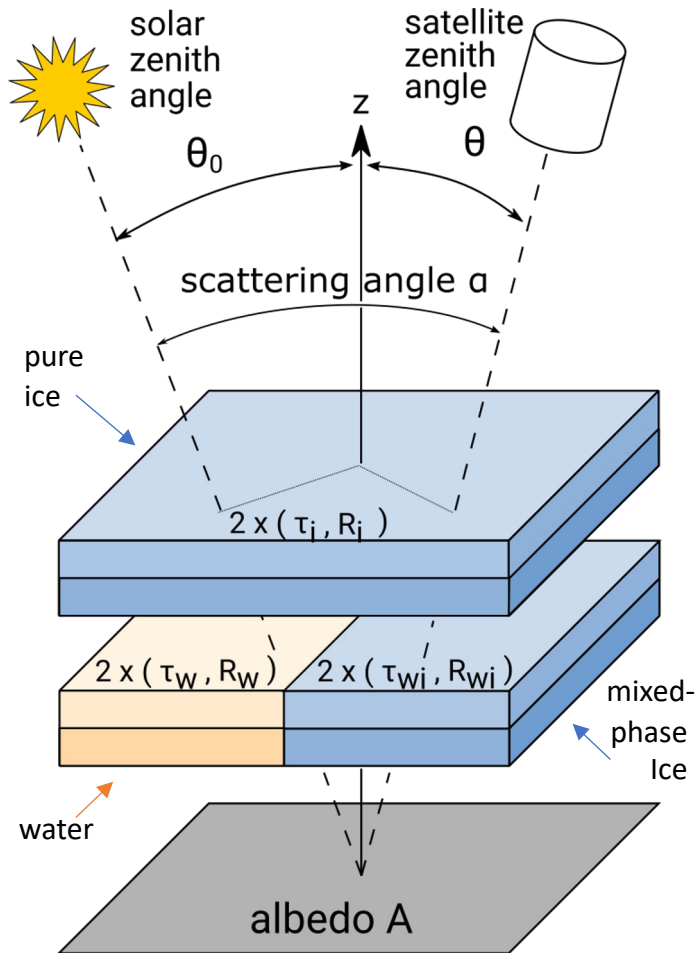
Adjoint / tangent linear codes

- Adjoint (AD) + tangent linear (TL) versions of the nonlinear NN inference code (NL) are required for variational and hybrid DA methods. → AD+TL implemented for Fortran code
- Advantage of neural networks: **AD/TL codes easy to derive, do not have to be modified** when training data or network structure is changed.



For more details see Scheck, L., 2021: *A neural network based forward operator for visible satellite images and its adjoint*, Journal of Quantitative Spectroscopy and Radiative Transfer, DOI:10.1016/j.jqsrt.2021.107841

Additional input parameters for the 1.6 μm channel



Interesting for DA & model eval.: 1.6 μm can distinguish water from ice, is sensitive to particle size

- Stronger sensitivity to effective radius profiles
→ use **two-layer clouds** to provide information on vertical effective radius gradients
 - (Dark) ice in mixed-phase clouds is often below water
→ add a two-layer **mixed-phase ice cloud** in the same location as the water cloud
 - Weak absorption by CO₂, CH₄
→ use **surface pressure and cloud top pressure** as input parameters to quantify influences
 - Weak absorption by water vapor
→ use **integrated water vapor** as input parameter
- **In total 16 input parameters** -- feasible with NNs, 16-dimensional LUT would have been very problematic.

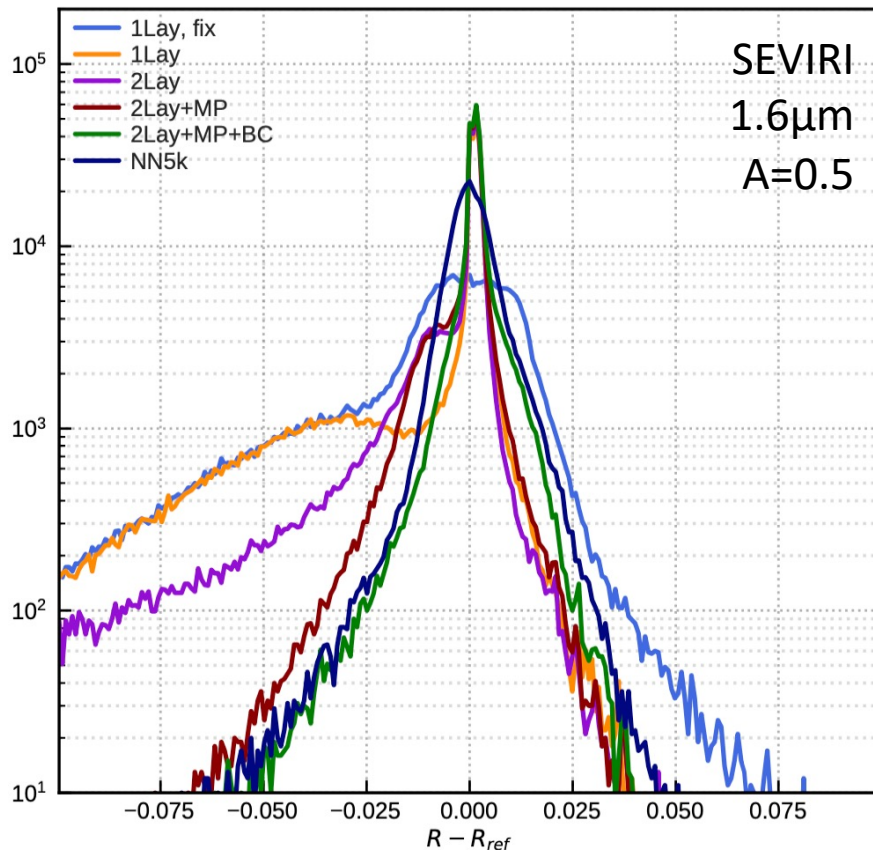
NN learns more complex function → 2.5 times larger NN and 4 times more training data required than for 0.6 μm .

Profile simplification and network training errors

Evaluation with IFS profile collection available from NWP SAF

Simplification error: Reflectance error caused by replacing full profiles by idealised profiles (both reflectances computed with DOM reference RT method), $R_{full} - R_{ideal}$

MFASIS-NN error: Simplification error + error caused by imperfect network training



Simplification error for idealised profiles with

(1) One-layer clouds at fixed height (7 param.)

(2) + surface & cloud top pressure, integrated WV (10 param.)

(3) + two-layer clouds (12 param.)

(4) + mixed-phase ice in water cloud (all 16 param.)

(5) + bias correction
 → MAE 0.003, 99th percentile 0.024

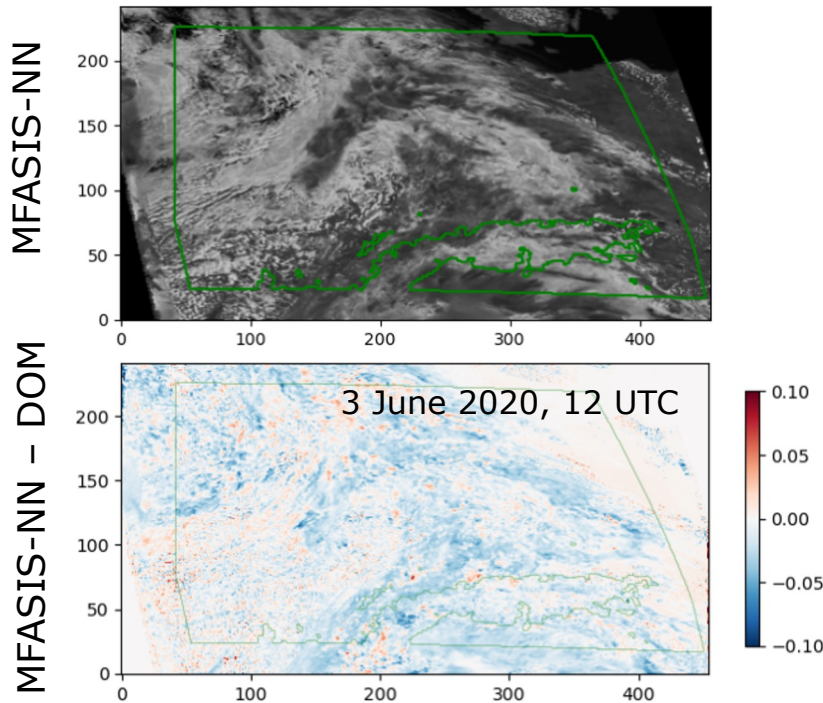
→ all new input parameters reduce errors

MFASIS-NN (training data based on (5)):
 MAE 0.004, 99th percentile 0.027

→ additional training error is relatively small (for a well-trained 5000 parameter NN)

more input parameters ↓

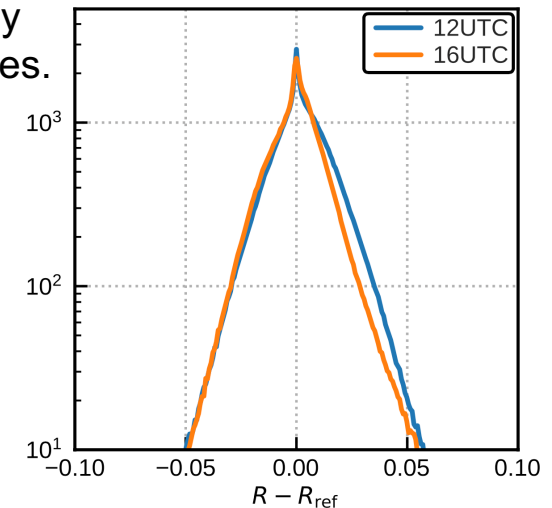
MFASIS-NN SEVIRI 1.6 μ m results for ICON-D2 forecasts



- Evaluation w. independent, regional model (30 days)
- For IFS profiles parameterizations for effective radii were used, but here **2-moment microphysics scheme** provides prognostic information on radii

| | Mean absolute error | 99th percentile |
|-------------------|---------------------|-----------------|
| 5000 IFS profiles | 0.010 | 0.035 |
| ICON-D2 (12UTC) | 0.011 | 0.046 |
| ICON-D2 (16UTC) | 0.013 | 0.056 |

Statistics are only slightly worse than for IFS profiles.

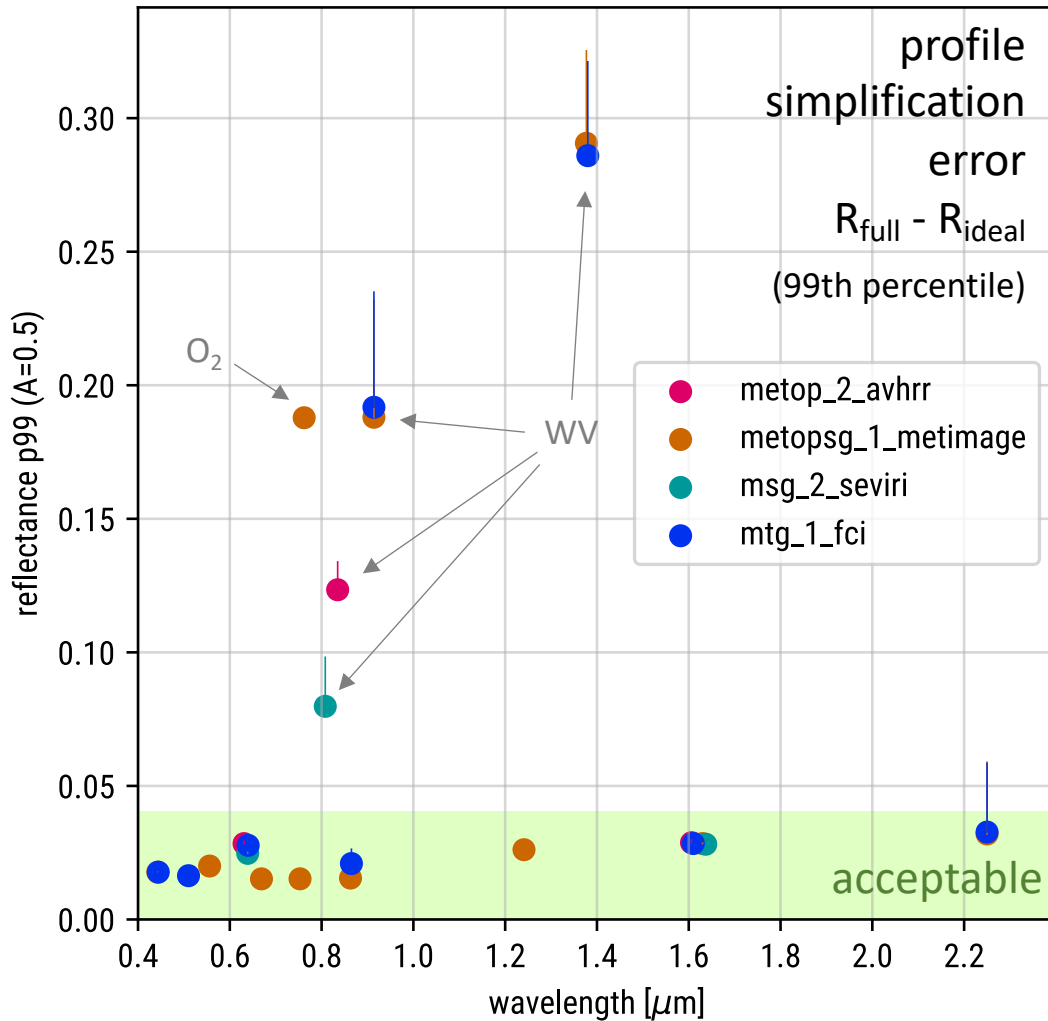


Summary: 1.6 μ m works -- errors are now similar to 0.6 μ m errors

For more details see Baur F. et al., 2023: *A neural network-based method for generating synthetic 1.6 μ m near-infrared satellite images* (submitted to AMT)

Except for WV input variable and vectorization everything is in **RTTOV 13.2**.

Other instruments and channels

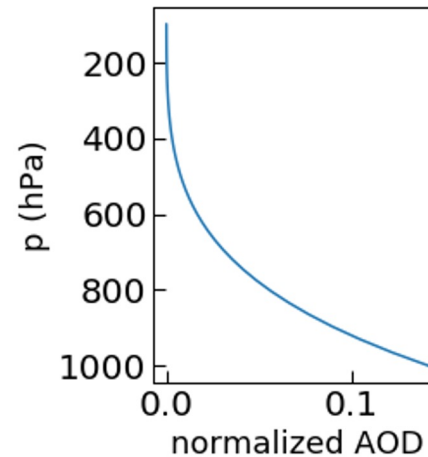


- **Examples:** Solar imager channels on MSG, MTG, MetOp, MetOp-SG
- **$\lambda \leq 0.7\mu m$ channels work well** (enough information on Rayleigh scattering in pressure input variables)
- **Weakly WV-affected channels also work well** ($2.2\mu m$, $1.6\mu m$, $1.2\mu m$ and most $0.8\mu m$ channels)
- **Errors are still too high for stronger WV sensitivity:** $1.3\mu m$, $0.9\mu m$, broad $0.8\mu m$ channels (MSG, MetOp) → will be solved by additional WV input parameters
- Channels affected by other absorption lines/bands will also need additional input parameters (e.g. $0.76\mu m$, oxygen A band)

First results for aerosols (preliminary)

A prototype based on CAMS aerosols

- Can we generate reflectances for arbitrary combinations of many aerosols species with one NN and still have sufficiently small errors?
- Same strategy as for clouds:
Replace complex aerosol profile by simplified version with same AOD, scale height, surface pressure and relative humidity
- First tests: Assume power law profile for extinction
- Prototype with **23 input variables** (incl. AOD + scale height for 9 CAMS species), NNs with 8 layers, 36 nodes/layer (a bit larger than for clouds, still fast -- <1μs/sample)

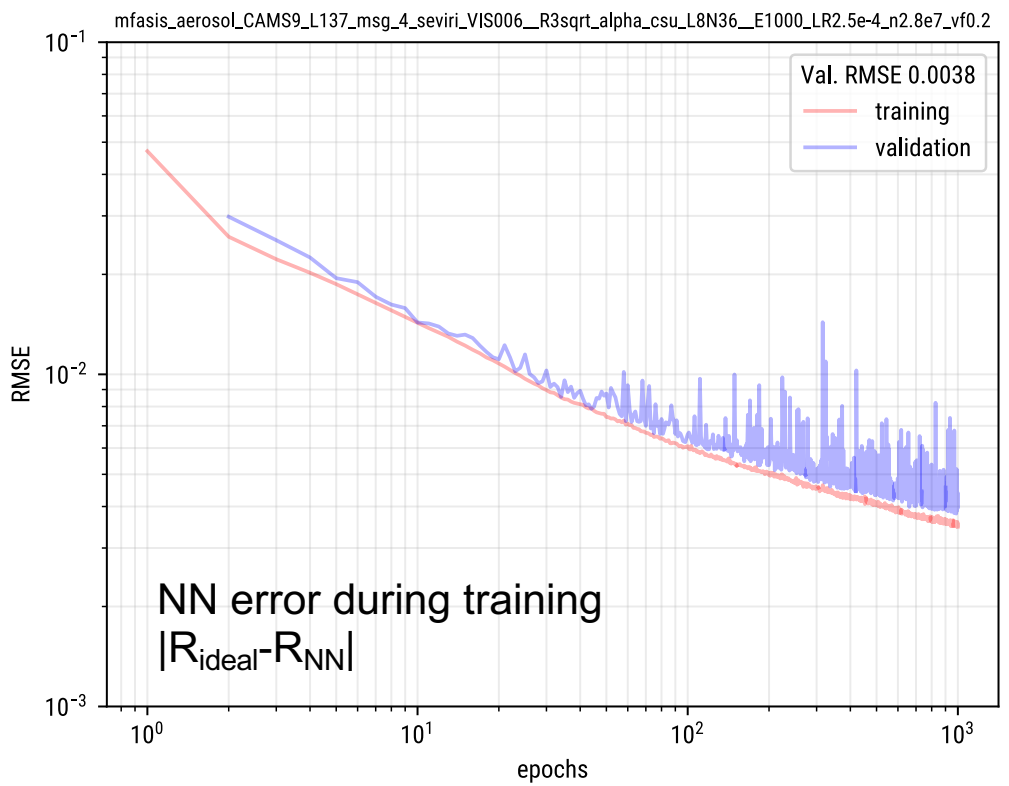
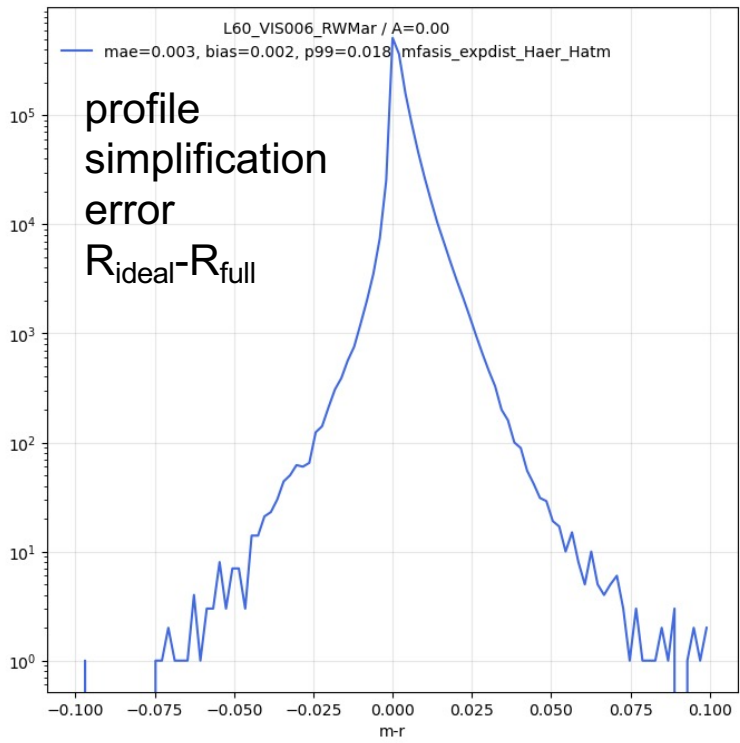


$$\beta_{ext} \propto \left(\frac{p}{p_0} \right)^{H_{atm}/H_{aer}}$$

- p_0 ... Surface pressure
- H_{atm} ... Scale-height atmosphere
- H_{aer} ... Scale-height aerosol
- β_{ext} ... extinction coefficient

First results for aerosols (preliminary)

Evaluation with MACC-60L data set (5 x 4000 IFS profiles optimized for different species):
Profile simplification errors are similar to cloud case (mean abs. reflectance error 0.003)



NN with 10⁴ parameters can be trained to error levels similar to cloud case → **promising...**

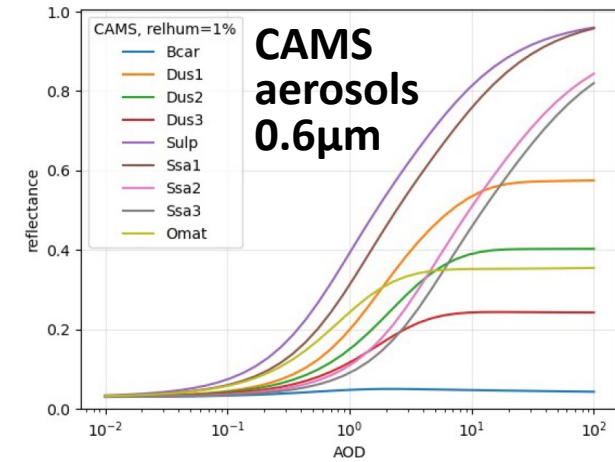
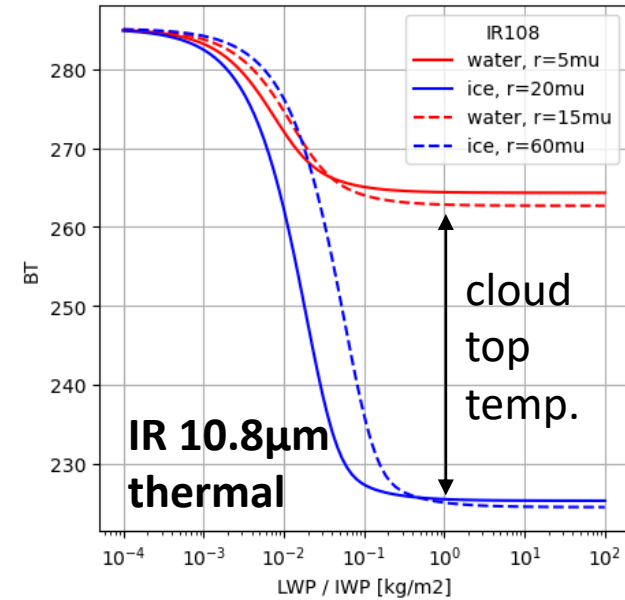
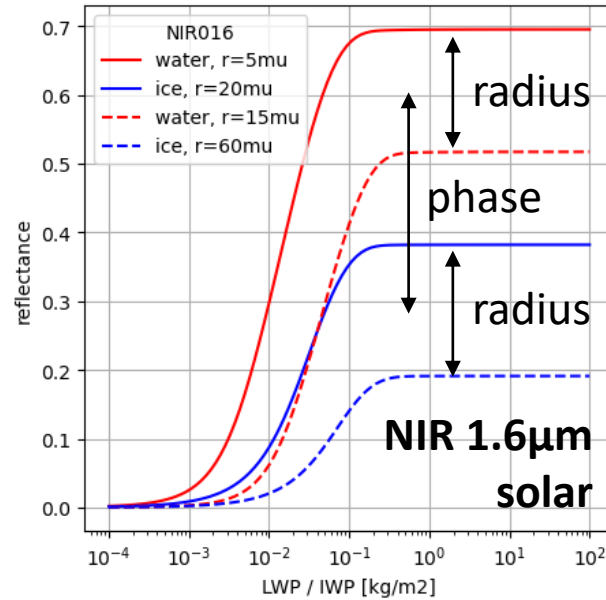
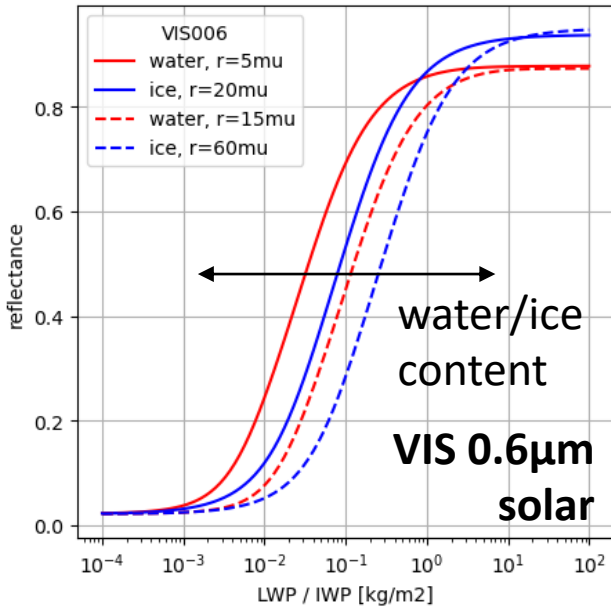
Summary

- Replacing a compressed look-up table by a **neural network** in a forward operator for solar satellite channels **has significant advantages** in terms of speed, memory consumption, number of input parameters and time required to generate training data
- **MFASIS-NN for clouds** with additional input parameters **yields good results** for the 1.6 μ m channels and many other channels. The new developments have been implemented in RTTOV 13.2 (except for WV input variable and code vectorization)
- A prototype of **MFASIS-NN for CAMS aerosols looks promising**
- Research at HErZ/LMU and DWD will continue. In particular, we plan to
 - finish first aerosol version, support further channels (in particular WV sensitive)
 - use feature extraction capabilities of neural networks for more complex channels
 - include 3D radiative transfer effects in neural network

Publications

- Baur F. et al., 2023: A neural network-based method for generating synthetic 1.6 μ m near-infrared satellite images (submitted to AMT)
- Scheck, L., 2021: *A neural network based forward operator for visible satellite images and its adjoint*, Journal of Quantitative Spectroscopy and Radiative Transfer, DOI:10.1016/j.jqsrt.2021.107841
- Scheck, Weissmann, Mayer (2018): *Efficient methods to account for cloud top inclination and cloud overlap in synthetic visible satellite images*, JTECH, Vol. 35, Issue: 3, p. 665-685.
- Scheck, Frerebeau, Buras-Schnell, Mayer (2016): *A fast radiative transfer method for the simulation of visible satellite imagery*, Journal of Quantitative Spectroscopy and Radiative Transfer, 175, p. 54-67.

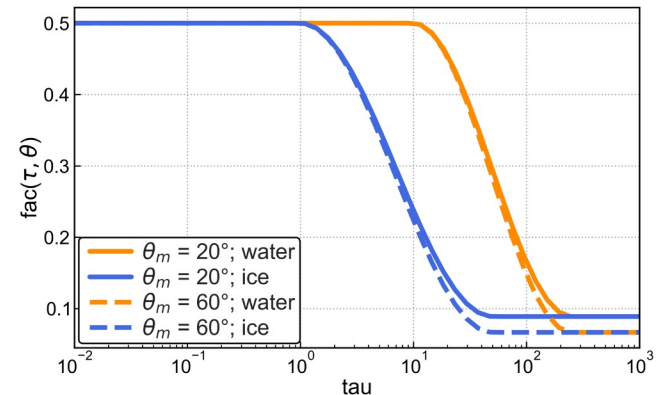
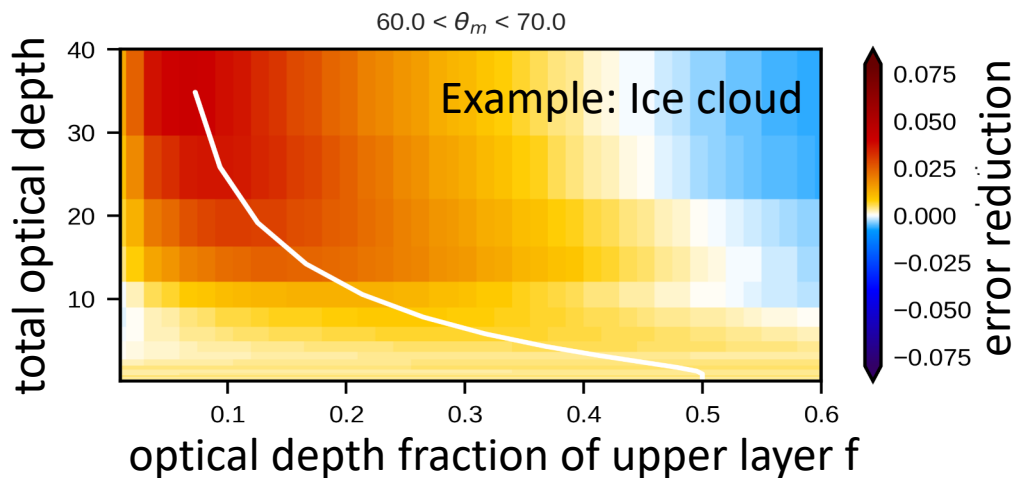
Why are we interested in solar channels?



- High-res. cloud information (also for low clouds, complementary to thermal channels) for improving forecasts (including radiation)
 - Aerosols (optical properties differ significantly)
 - Channels sensitive to water vapor, O₂, ...
- Challenges: Multiple scattering, 3D effects**
- Standard radiative transfer methods too slow for DA

How to split clouds in two layers

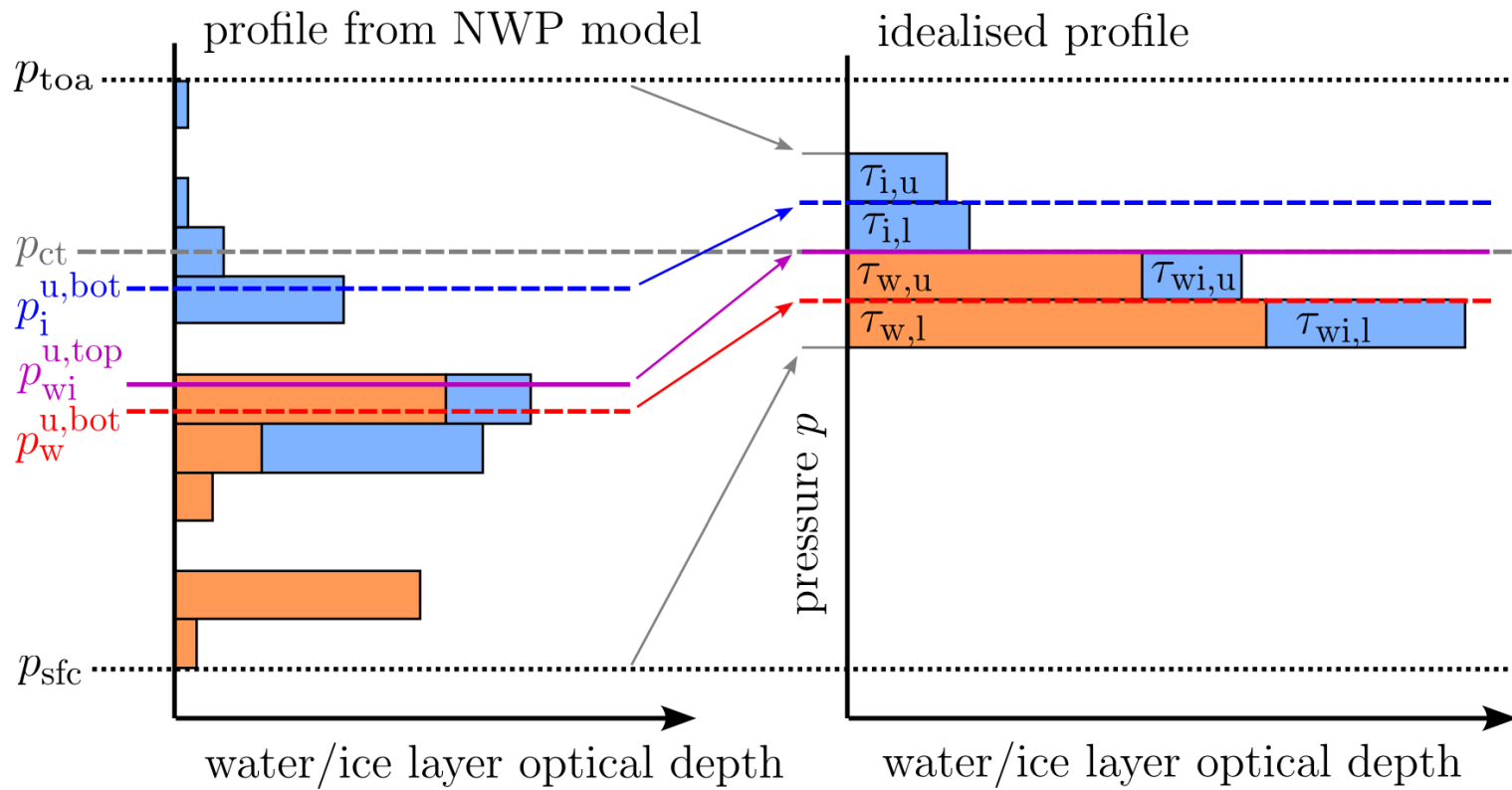
- 50% + 50% of optical depth for thin clouds (same probability to be scattered)
- Thicker clouds: e.g. upper 10% + rest, because deeper layers contribute less to reflectance and it is more important to resolve effective radius gradients near the top of the cloud
- Aim: Maximize error reduction, compared to one-layer clouds
- Error reduction computed for collection of 5000 IFS profiles sampled from one year of global IFS short-term forecasts (maximizing diversity in cloud profiles). 64 random angle combinations were used for each profile. Effective radii computed with parameterizations.
→ Parameterization for near-optimal depth fraction of upper layer f



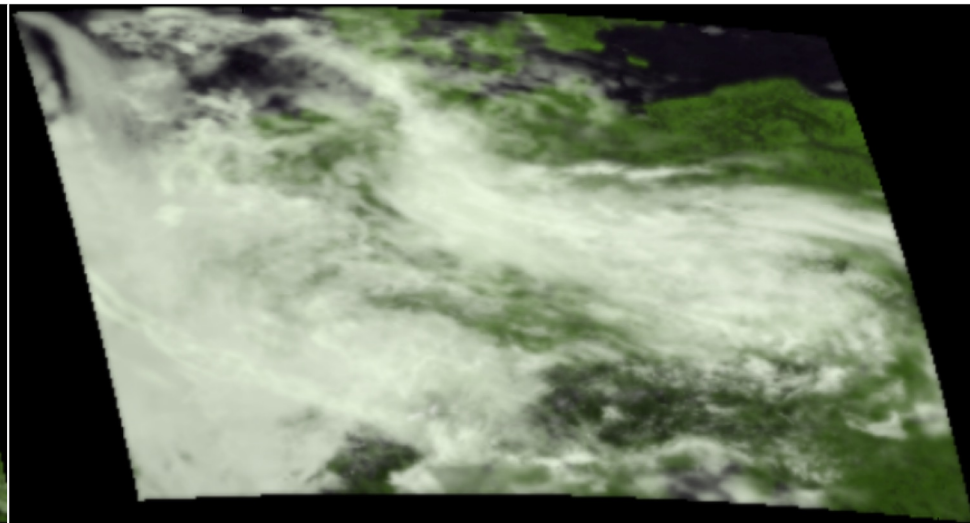
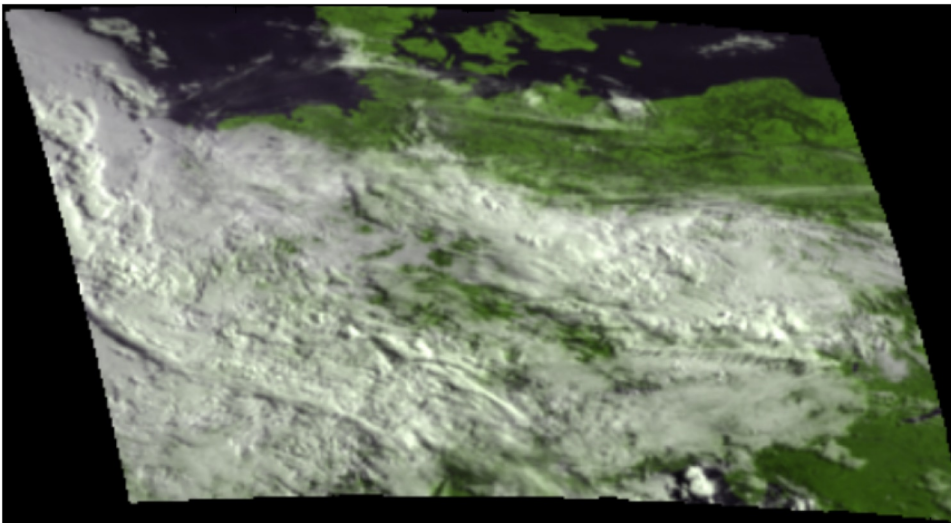
Parameterization of the fraction as function of optical depth, zenith angle

How to compute parameters from NWP profiles

- Cloud top height is where cloud optical depth exceeds 1
- Boundary between water-or-mixed-phase / pure ice cloud determined by water cloud optical depth > 0.5 threshold
- Boundaries between lower / upper cloud layer for water/ice determined by parameterization



Taking cloud top inclination into account (3D RT effect)



SEVIRI 0.6 μ +0.8 μ , 3 June 2016, 6UTC

3h COSMO fcst **without 3D correction**

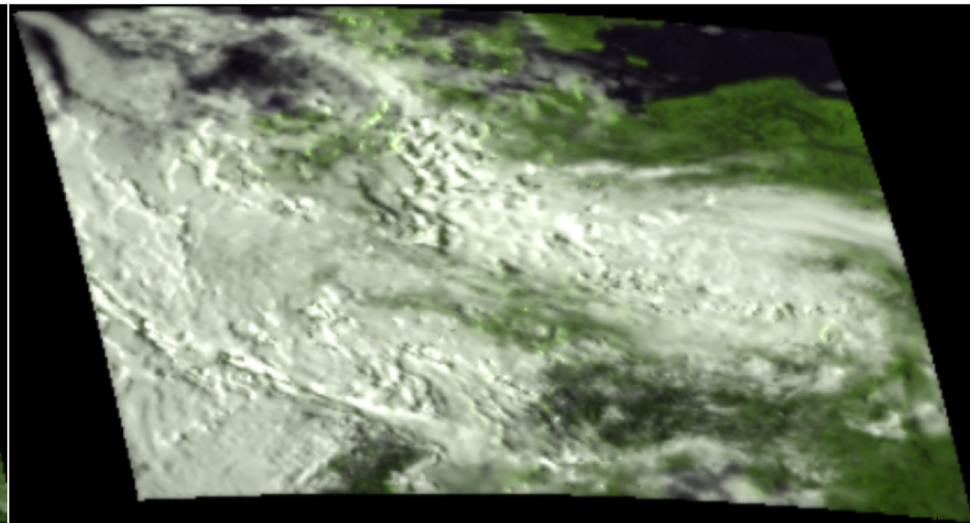
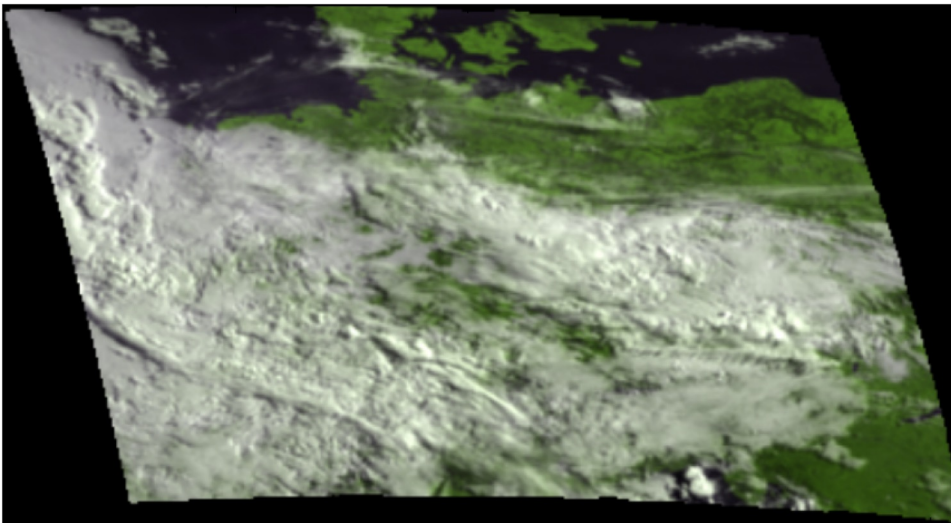
Cloud top tilted away from/towards sun \rightarrow reflectance lower / higher

Fast approximation: Find optical depth 1 surface, determine inclination angles
Compute 1D RT solution in rotated frame of reference (in which inclination is zero),
transform reflectance back to non-rotated frame

Cloud top inclination correction \rightarrow Reduced errors, increased information content

Much more cloud structure is visible, in particular for larger SZAs

Taking cloud top inclination into account (3D RT effect)



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