

CLOUD CHARACTERISTICS AND CHANNEL SELECTION FOR IASI RADIANCES IN THE METEOROLOGICALLY SENSITIVE AREAS



Nadia Fourrié and Florence Rabier
 Centre National de Recherches Météorologiques, Météo-France
 Nadia.Fourrie@cnm.meteo.fr

Cloud characteristics in meteorologically sensitive areas

Channel selections in the sensitive areas

*IASI=Infrared Atmospheric Sounding Interferometer developed by CNES-EUMETSAT

*Advanced IR sounders
 -large volume of data, prohibitive in operational NWP-> reduced channel set used in operational context.

*Sensitive areas: where small changes in the analysis can drastically change the forecast. IASI can resolve some of the small structures identified by sensitivity studies (Rabier et al, 96, Prunet et al. 1998, Collard, 1998).

* Selection of individual channels

*At each step, one channel is picked. It is the most informative channel among those which have not been previously selected.
 *The analysis error covariance matrix is then updated

*McNally (2002) showed with ECMWF model clouds that sensitive areas are widely covered by high-level and low-level clouds.

* Iterative Method (Rodgers, 1996 and Rabier et al, 2002) or Entropy Reduction (ER) method
 ✓ This method is a step by step iterative selection scheme, based on information content wrt the background information.

*Is it true for clouds seen by the imager AVHRR in the IASI pixel? MAIA (Mask AVHRR for Inversion ATOVS) method used for FASTEX cases.

- The selection criterion is ER
- $ER = -1/2 \log_2 \det(AB^{-1})$
- Where B= background and A= analysis error covariance

✓ «Constant» selection obtained by averaging the ranks of the channels
 Cst selection = Ave (Selection i)

* Channel selections based on targeting strategy

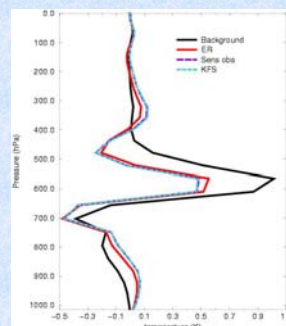
* Sensitivity to observations (Baker and Daley, 2000; Doerenbecher and Bergot, 2001). Channel selected wrt the maximization of the sensitivity to observations $\nabla_{y_o} J$:

* $\nabla_{y_o} J = r_i^T A_i \nabla_{x_a} J$
 Where r_i is the error value, h_i^T is the vector corresponding to a line of the Jacobian matrix, $\nabla_{x_a} J$ is the sensitivity to initial conditions

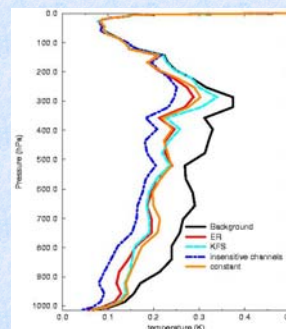
* Kalman Filter Sensitivity (Bergot and Doerenbecher, 2002). Channel selected wrt the maximum decrease of the variance of the error on a given scalar function of the forecast $\delta\sigma$:

$$*(\delta\sigma)^2 = \nabla_{x_a} J B_{i-1} h_i^T (r_i + h_i^T B_{i-1} h_i)^{-1} h_i^T B_{i-1} \nabla_{x_a} J$$

Deviations from the true temperature for 1 representative profile for the background and 3 different analyses.
 «Background» refers to the background error, «ER» to the analysis error obtained with the Entropy Reduction method, «Sens obs» to the analysis error given by the sensitivity to observations method and «KFS» to the analysis error produced by the Kalman Filter Sensitivity method.



> Background error large in the 400-900hPa layer and maximum located at about 550hPa. Another relative maximum at 700 hPa.
 > 3 methods largely decrease the analysis error compared with the background one. Slight degradation observed in the 650-750hPa layer. Both methods based on adjoint gradient give better results around the mean error peak.

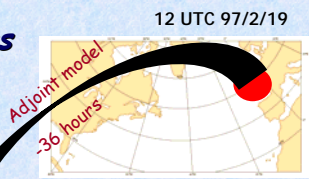


Root mean Square errors for 4 channel selection methods averaged over 142 profiles corresponding to a cloud top level of 1000hPa. «Insensitive channels» corresponds to the assimilation of all the channels not contaminated by low level cloud effects (about 2140 channels, number depending on the profile). «Constant» corresponds to an analysis computed with a constant channel set for clear sky condition but channels contaminated by cloud effect have been removed (about 220 channels, depending on the profile).

> Slight degradation observed in the troposphere with the constant channel set in comparison with an optimal channel set.
 > The assimilation of all the channels insensitive to cloud effects give an improvement of about 0.03K
 > KFS better than constant, but not better than ER

Sensitive areas

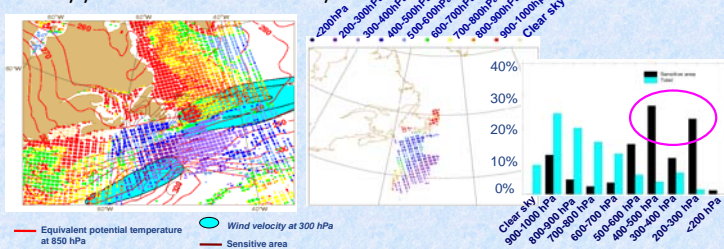
Diagnostic function: forecast of the mean sea level pressure over the region of interest on 19 Feb 1997, 12 UTC



Sensitive area determined with temperature fields of the gradient of the diagnostic function with respect to initial conditions (18 Feb 1997, 0 UTC)

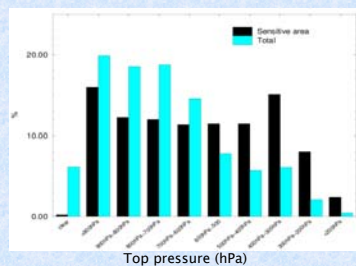
Example for IOP 17 (UTC 18/2/97)

Cloud top pressure of the simulated IASI pixels



•Large amount of cloud top level above 600 hPa observed in a wide southern part of the sensitive area
 •Low-level clouds are present in the northern part.

Overview over 8 FASTEX cases.



Average distribution of the cloud top height of the IASI pixels over 8 sensitive areas of the FASTEX Intensive Observing Periods and on the whole data set corresponding to a mid-latitude region.

>For sensitive areas, 2 maxima in the distribution observed : 1000-900 hPa and 400-300hPa atmospheric layers.
 >For the whole IASI dataset, 60% of the cloud tops are situated below 600 hPa.

Conclusions

•The simulated IASI pixels located in the sensitive areas are usually covered by low-level clouds and by high-level clouds

•Channel selection of Rabier et al 2002 study compared with two method derived from targeting strategy (sensitivity to observation and Kalman filter sensitivity). Iterative method based on Entropy Reduction (ER) shares few channels with the two other ones but is quite robust even for highly sensitive profiles.

•Constant channel set computed from an independent set of atmospheric profiles leads to a significant improvement of the analysis compared with the background even if the analysis error is larger than the one obtained with an optimal channel set.

Future work

•Taking into account the clouds in the radiative transfer model for the channel selection
 •Assimilation of the IASI radiances in the NWP assimilation scheme → test of the actual impact of the different channel selection on the forecast score.

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