

# AVHRR operational cloud masks intercomparison

## CLAVR-x

The Clouds from AVHRR Extended (CLAVR-x) series of algorithms are designed to serve two roles in the NOAA/NESDIS AVHRR processing. First it serves as the first guess cloud mask for other NESDIS applications. Secondly, it provides a full suite of global cloud properties from the AVHRR.

- The main characteristics of CLA VR-x are
  - The cloud mask reports a 4-level decision - clear, probably clear, probably cloudy and cloudy
  - Spatial uniformity tests are used to reduce cloud contamination in clear and cloudy pixels.
  - 6 cloud types are produced (fog, water, super-cooled water, opaque ice, cirrus and multi-layer cirrus)
  - NWP, SST weekly analyses and a Fast RTM model (PFAST) are used in cloud detection and cloud property estimation.
  - 1d var approaches are used for all cloud retrievals
  - Cloud temperature and emissivity estimated from a split-window approach.
  - Other products include optical depth and particle size.
  - Products are available regionally at 1 km and globally at 4 km (pixel) or 55 km (gridded).

Description available on <http://cimss.ssec.wisc.edu/clavr>

## MAIA

The MAIA cloudmask is developed at Météo-France. It is operational at CMS for processing NOAA polar AVHRR data. MAIA V2 is incorporated in EUMETSAT Numerical Weather Prediction SAF AAPP package. MAIA V3 will be used for the operational production of SST at a global scale in the Ocean & Sea Ice SAF and is planned in AAPP early 2007 for NOAA and MetOp processing after a MetOp global validation stage. For NOAA, MAIA V3 has been validated to interactive classified targets.

- Four products are available:
- Cloud Mask with a confidence flag
  - Cloud Type (10 classes)
  - Cloud top temperature of opaque clouds
  - SST

- The main characteristics of MAIA are:
- Grouped thresholding approach
  - Dynamic thresholds derived from RTM (through look-up tables)
  - Use of ancillary data: SST and albedo climatologies, Landuse and topography maps, NWP forecast parameters.
  - Many different spectral features (single channels and ratios and differences) + texture
  - Products are available at 1 km resolution in the AAPP output format.

Description on <http://www.meteorologie.eu.org/ici>

## PPS

The Polar Platform System (PPS) software package is developed at SMHI in the frame of the EUMETSAT Nowcasting SAF to process data of polar (NOAA/MetOp) platforms in Europe. Four products are available:

- Cloud Mask
- Cloud Type
- Cloud top temperature and height
- Precipitating clouds

The main characteristics of the PPS Cloud Mask and Cloud Type are very similar to those of MAIA. The version 1.0 of PPS to produce all these four products using locally received HRPT data was released to Eumetsat member (and cooperating) states in June 2004.

PPS is currently run in operational mode at six European Met Services including the Ocean & Sea Ice SAF High Latitude center and the Climate SAF for cloud parameters at high latitudes.

Recently its scope has been widened to the global scale. It has been validated over Europe by comparing results to interactive classified targets, and using a large database of European Synop reports.

The PPS is coded in Python, C and Fortran (interfacing to AAPP, RTTOV and Grib). The output format is HDF5.

Description on <http://www.smhi.se/saf>

## CLAVR-x – MAIA – PPS intercomparison over European passes

### Motivation

Operational satellite cloud classification from AVHRR at Eumetsat has traditionally been limited to 1 km locally received HRPT data and from various processing centers simultaneously at Meteo-France/CMS and SMHI and the corresponding NOAA LAC data for 6 different days in July 2006.

Eumetsat will soon launch MetOp, which will provide the first global 1 km data from AVHRR. MetOp also represents a new level of cooperation between NOAA and Eumetsat in terms of data sharing.

The goal of this work is to intercompare the AVHRR cloud algorithms run operationally by NOAA and Eumetsat and to begin a collaboration to jointly improve our ability to estimate cloud properties from the AVHRR.

### Data

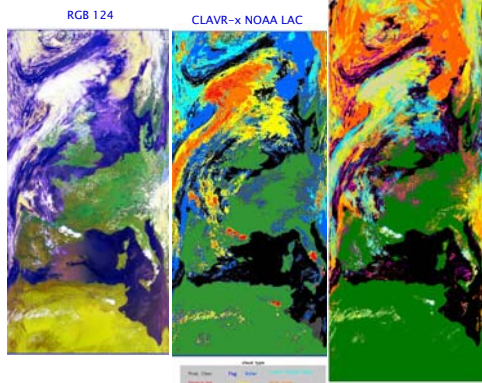
The intercomparison activity has just started and the present results have been done on 7 scenes:

- 6 full daytime NOAA18 HRPT summer scenes acquired simultaneously at Meteo-France/CMS and SMHI and the corresponding NOAA LAC data for 6 different days in July 2006.
- 1 full NOAA17 HRPT winter case from SMHI station and the corresponding NOAA LAC data.

The classification convention is the same for MAIA and PPS but is slightly different in CLA VR-x. To conduct the intercomparison, we made the following assumptions:

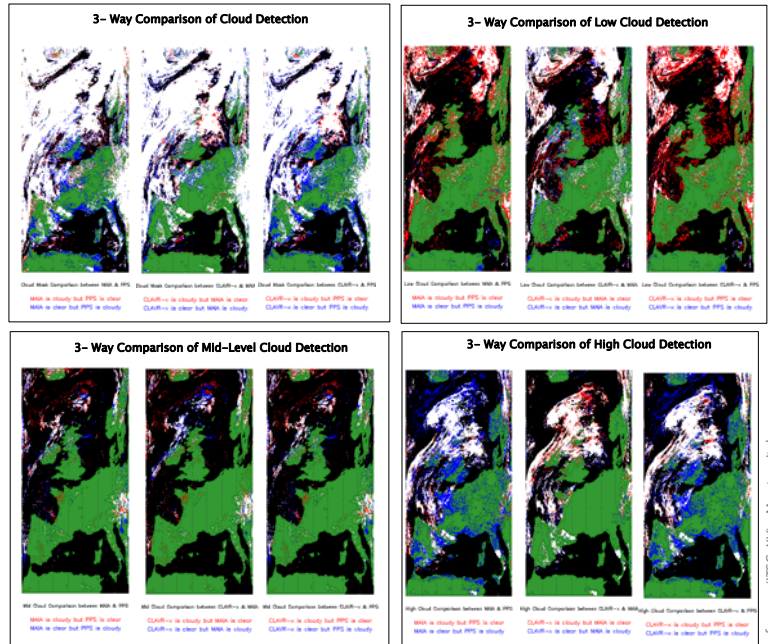
- Cloud mask, Clear:
  - clear, probably clear (CLA VR-x)
  - cloud free sea, land / snow or sea ice covered (MAIA & PPS)
- Low clouds:
  - Clouds with pressures greater than 680 hPa (CLA VR-x)
  - Very-low, Low opaque clouds ( $T_{cloudtop} > T_{700hPa}$ ), fractional (MAIA & PPS)
- Mid clouds:
  - Clouds with pressures between 440 and 680 hPa (CLA VR-x)
  - Mid, high opaque clouds ( $(T_{500hPa} + T_{700hPa})/2 < T_{cloudtop} < T_{700hPa}$ ), (MAIA & PPS)
- High clouds:
  - Clouds with pressures less than 440 hPa (CLA VR-x)
  - Very high opaque, very thin, thin, thick cirrus, cirrus above others, fractional (MAIA, PPS)

Ex: NOAA18 – 2006-07-01  
12:52 UTC



### Statistical agreement over the 7 orbits

Sea. fraction of data = 0.51				
Comparisons	M & C	P & C	P & M	
cloud mask agreement =	0.922	0.918	0.941	
high cloud agreement =	0.929	0.858	0.892	
mid cloud agreement =	0.919	0.910	0.932	
low cloud agreement =	0.924	0.896	0.929	
Land. fraction of data = 0.49				
Comparisons	M & C	P & C	P & M	
cloud mask agreement =	0.890	0.833	0.836	
high cloud agreement =	0.934	0.773	0.779	
mid cloud agreement =	0.931	0.928	0.921	
low cloud agreement =	0.895	0.920	0.900	



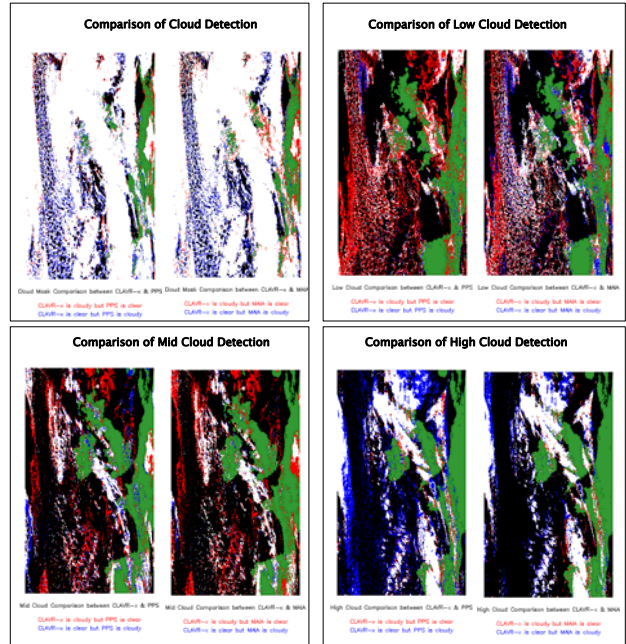
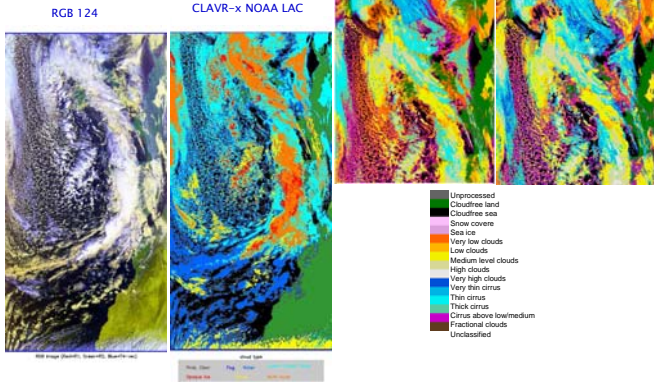
### Conclusion

- Over water, all three cloud masks agree over 90% of the time
- Over land, all three cloud masks agree over 80% of the time though the agreement between CLA VR-x and MAIA approaches 90%.
- For layered cloud detection the best agreement (93%) is found for high clouds over land between CLA VR-x and MAIA. Here the agreement with PPS falls below 80%.
- Except for high clouds over land, the levels of agreement are quite uniform with all values being around 90%.



# CLAVR-x – MAIA – PPS intercomparison

Ex: NOAA17 – 2006-01-15  
11:30 UTC



## MAIA - PPS comparison and convergence over interactive marine targets

### Motivation

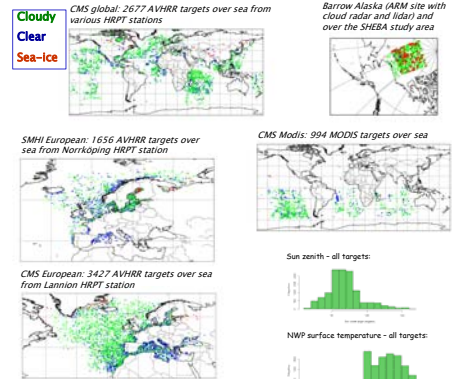
As part of the OSI SAF Global Metop/AVHRR SST development a special WP was set up to compare the MAIA and the PPS cloudmasks. Work done before CLAVR-x/MAIA/PPS intercomparison. The aim was to:

- validate and improve when necessary the MAIA cloudmask over sea prior to the implementation in the OSISAF chain.
- secure a general high quality and coherency between the two different schemes.

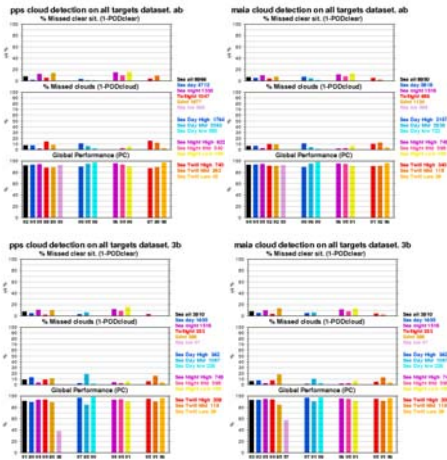
### Data

Oceanic datasets with AVHRR training and validation targets interactively collected by experienced nepheloylist and guided by other ground based remote sensing data (cloud radar/lidar):

- Training and validation data
  - CMS Global
  - SMHI European
  - SMHI Arctic
- Validation data
  - CMS European
  - CMS Modis
- For visual inspection
  - 6 full HRPT scenes from La Reunion
  - 6 full HRPT scenes from Kangerlussuaq



### Results after updating both MAIA and PPS over sea



**Statistical scores**

- Hit rate:  $PC = (n_c + n_d) / (n_c + n_e + n_d)$
- Rate of missed cloudy situations:  $(1-POD_{cloud}) = (n_e / (n_c + n_e))$
- Rate of missed clear situations:  $(1-POD_{clear}) = n_e / (n_c + n_e)$

	Cloud detected	Clear detected
Cloud observed	$n_a$	$n_b$
Clear observed	$n_c$	$n_d$

- MAIA and PPS cloudmasks proved very similar over sea
- Most of the problems identified at the start of this project have been solved for both masks:
  - About 92–94% of clear+cloudy situations are correctly classified
  - Only about 5% of clouds and 5% of clear situations are missed
- MAIA cloud detection slightly more severe compared to PPS
  - An additional test exists in MAIA with a relaxed threshold on the local texture → "marine" cloud mask to allow O&SI to monitor sea surface thermal fronts
- This study pointed to some remaining cloud detection problems over sea:
  - Ice-detection using 3b for both schemes. (But more interactive targets needed.)
  - Semi-transparent cirrus cloud detection over sea ice difficult for both schemes
- The problems related to cloud detection in the polar night not sufficiently challenged with this dataset

Detailed report on: <http://www.osi-saf.org>

