Assimilation of AMSU-B Radiances In the HIRLAM 3DVAR Analysis ITSC-15 2006. Maratea, Italy.

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HIRLAM: HIgh Resolution Limited Area Model

LAM model used for operational forecasting and research in: Sweden, Finland, Norway, Denmark, Ireland, The Netherlands, Spain

EXPERIMENT SETUP

Period: January 2005

ANALYSIS

3DVAR Background error structure functions based on analytical balance FGAT (First Guess at Appropriate Time) 6h assimilation cycle

REF: Conventional observations + AMSU-A EXP: REF+ AMSU-B from NOAA16

FORECAST MODEL

33km horizontal resolution 40 vertical levels Semi-Lagrangian semi-implicit dynamics Kain-Fritsch (convection) Rasch-Kristjánsson (stratiform) CBR (turbulence) ISBA (surface scheme)



OBSERVATION ERRORS			
	Approximated background error (BGOS)	Assigned observation error	Weight given in analysis σ_b/σ_o (approx)
CH 3	3.5 K	2.0K	1.75K
CH 4	2.0K	2.0K	1.0
CH 5	1.5K	2.0K	0.75

BIAS CORRECTION

p₀: constant c: coefficients, calculated from a reference data-set P: predictors

Predictors:

- Mean temperature 1000-300hPa
- Mean temperature 200-50 hPa
- Square of scan-angle
- Scan-angle

Data from December 2004 were used to calculate the coefficients



x-axis: (y-Hx_b) [K] y-axis: number of samples Blue: overlayed gaussian curve Red: data distribution



Uncorrected innovations

QUALITY CONTROL

Scattering will influence the AMSU-B measurements if there is rain or ice particles.

Ch1 – Ch2 is used a (crude) index to spot, and remove, such observations: Ch1 –Ch 2 >-15K → reject



Ch 134



AMSU-B CH1-Ch2



AMSU-B Ch1-Ch2 >-15K

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AVHRR RGB image

