

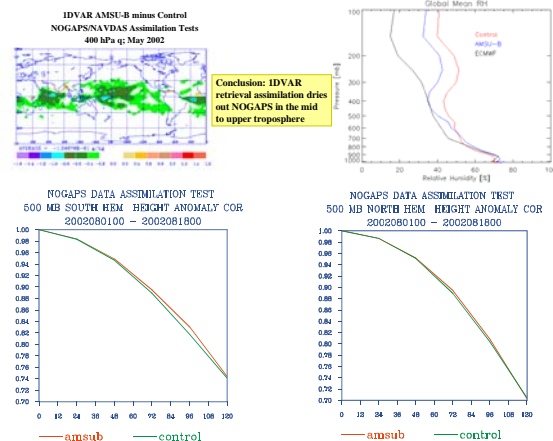
AMSU-B Radiance Assimilation for NOGAPS and COAMPS

Motivation

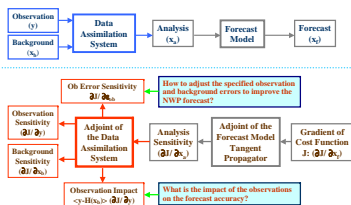
- NOGAPS and COAMPS use few observations of mid- to upper-tropospheric humidity
- Assimilate water vapor profiles from AMSU-B microwave observations
- Approach
 - Observations from the AMSU-B microwave radiometer on the NOAA-16 polar orbiter.
 - 150 GHz and 183.31±1, 3, and 7 GHz channels
 - Thinned to every fourth scan (May 2002 runs) or one ob per 2x2° degree box spacing in tropics (equivalent higher latitudes) for August 2002 runs.
 - Land, coast, and sea ice are screened out, as are points with high scattering index (Greenwald and Christopher, 2002).
 - Algorithm is a physical optimal estimation inversion of the observed brightness temperatures (based on Blankenfeld et al. (2000))
 - Equivalent to a one-dimensional variational assimilation (IDVAR) of radiances at each observation point.
 - NOGAPS background (6-hour forecast) humidity profile
 - Temperature profile, sea surface temperature, and surface wind speed from the NOGAPS forecast (held constant)
 - Clouds are turned off in this version of the retrieval
 - No bias correction known upper tropospheric moist bias in NOGAPS makes traditional bias correction techniques problematic
 - Retrievals which failed to converge (usually due to heavy cloud or precipitation in the scene), or which failed gross temperature departure checks were also rejected.
 - NAVDAS assimilates the IDVAR profiles of pseudo relative humidity
 - IDVAR used due to limitations with present NAVDAS configuration
 - Approximately 45,000 retrievals (5000 for August runs) from the NOAA-16 AMSU-B per 6-hour update cycle are assimilated.

Results

- Corrects NOGAPS tendency to be too moist above 500 mb
- Enhances humidity gradients in the Intertropical Convergence Zone and South Pacific Convergence Zone
- There is also an enhanced humidity gradient at 20° W off the western African coast. The stronger gradient there is consistent with the model's wind field, which indicates that the air mass origin is continental north of 10° N but maritime south of that.
- These enhanced gradients are largely maintained out to 4 days



NAVDAS Adjoint System



Data Assimilation Adjoint Theory

- Begin with the linear analysis equation

$$x_a = x_b + K(y - Hx_b),$$

where

$$K = BH^T (BBH^T + R)^{-1}$$

- The sensitivities of the analysis to the observations and background are

$$\frac{\partial x_a}{\partial y} = K^T,$$

$$\frac{\partial x_a}{\partial x_b} = (I - KH)^T.$$

- Using the chain rule, the sensitivities of the forecast aspect J to the observations and background are

$$\frac{\partial J}{\partial y} = \frac{\partial x_a}{\partial y} \frac{\partial J}{\partial x_a} = K^T \frac{\partial J}{\partial x_a},$$

$$\frac{\partial J}{\partial x_b} = \frac{\partial x_a}{\partial x_b} \frac{\partial J}{\partial x_a} = (I - KH)^T \frac{\partial J}{\partial x_a}.$$

Baker and Daley (2000)
Doerenbecher and Bergot (2001)

Observation Sensitivity Applications

- Diagnostic (observation taken and forecast error known)

- Impact of observations on forecast error
- Tuning of error variances and other parameters

- Targeting (observation and forecast error not known)

- Test the impact of hypothetical observations
- Potential benefit of satellite data prior to launch
- Alternative networks of satellite and in-situ observations

- NRL Core Systems – NAVDAS¹ and NOGAPS²

- NRL Predictability Research Group

- Daley and Barker (2000a,b)
- Hogan and Rosmond (1994); Rosmond (1997)

Observation Impact on NOGAPS Forecast Error

$$\delta e_{3d}^{30} = \left((y - Hx_b), \frac{\partial J}{\partial y} + \frac{\partial J}{\partial y} \right)$$

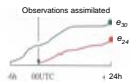
δe_{3d}^{30} = adjoint estimate of difference between the 30th and 24th forecast error in global model (scalar)

y = observation vector (~ 250,000 obs)

x_b = background (6h) forecast

- We want an estimate of the impact of the observations on the NOGAPS forecast error in observation space

Choice of Cost Function



- Observations are assimilated at 00UTC, creating initial conditions for a new trajectory, which has forecast error e_{24}

- The old trajectory starts from IMTC (e_{24}), and has forecast error e_{30} . It also provides the background for the analysis at 00UTC.

- Both forecasts verify at time +24h.

- The difference between the errors $e_{24} - e_{30}$ is due solely to assimilation of observations.

- Nonlinear forecast error is given by $\Delta e_{30}^{30} = e_{30} - e_{24}$, where $e_j = (x_j - x_b), C(x_j - x_b)$ and C is the total (dry) energy-weighted error norm.

- Quadratic measure forecast error ($J \text{ kg}^{-1}$) that combines temperature, wind and pressure from ~ 150 hPa to the surface

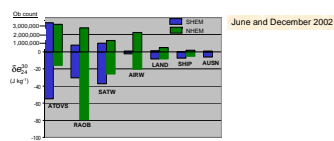
- NOGAPS at T79L30 resolution; verifying analyses produced by NAVDAS

- The impact function δe_{30}^{30} gives an estimate of the contribution of each observation assimilated by NAVDAS in the global domain to a reduction or increase in e_{30}^{30}

- For complete derivation, see Langland and Baker (2003)

- Furiat *et al.* (2002) and Doerenbecher and Bergot (2001) use similar cost functions

Global Observation Impact (by hemisphere)

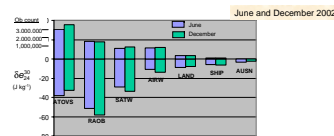


- Observation impact ($\delta e_{30}^{30} \text{ J kg}^{-1}$) for Southern and Northern Hemispheres, partitioned by instrument type

- Includes all observations assimilated in NAVDAS at 00UTC.

- ATOVS-temperature retrievals, RAOB rawinsondes, SATW-cloud and feature track winds, AIRW-commercial aircraft observations, LAND-land surface observations, SHIP-ship surface observations, AUSN-synthetic sea-level pressure data (Southern Hemisphere only).

Global Observation Impact (by season)



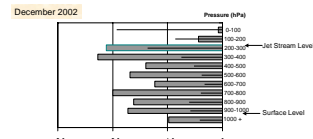
- Global observation impact ($\delta e_{30}^{30} \text{ J kg}^{-1}$) for June and December 2002

- Includes all observations assimilated in NAVDAS at 00UTC.

Acknowledgements

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Global Observation Impact (by vertical level)



- Global observation impact ($\delta e_{30}^{30} \text{ J kg}^{-1}$) partitioned by pressure level for December 2002.

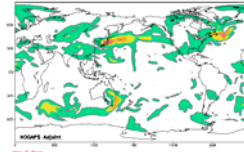
- Black solid line with gray bar: proportional to number of observations in each pressure layer

Sensitivity to Initial Conditions

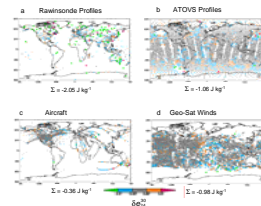
December 10, 2002

Sensitivity of 24h Forecast Error to ICs

Vertical Integral combining $\Delta u, \Delta v$



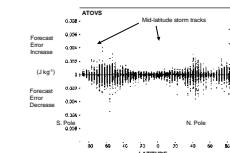
Global Observation Impact (J Kg-1) 00 UTC 10 December 2002



- Green: large reduction in 24h global forecast error. Red: large increase

- Blue: moderate reduction Orange: moderate increase Gray: small reduction or increase

Global Observation Impact for ATOVS



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