Validation of satellite hyperspectral L2 products with in situ measurements: a discussion of the collocation errors in the validation budget using GRUAN data. X. Calbet, M. Crapeau, T. August (EUMETSAT)

Cal/Val Strategy the Standard way

- 1. Collocation
- 2. Pre-processing
- 3. Comparison
 - ... but ...
- Collocation errors???
- Sonde humidity errors???

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Alternative Cal/Val Strategy

- 1. Collocation
- 2. Pre-processing
- 3. CONSISTENCY CHECK!! Assess their co-location and quality by doing an Observed versus Calculated radiance comparison
- 4. Comparison

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Nomenclature

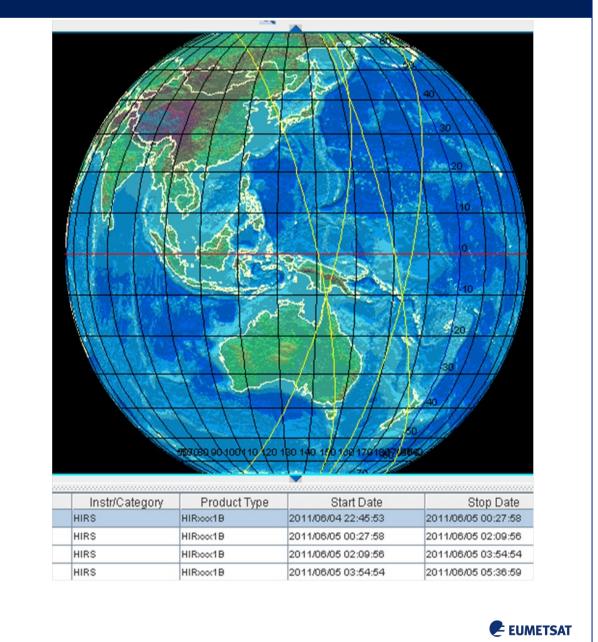
- Reference profile: ground based Remote
 Sensing, GRUAN Sondes, NWP profiles, etc.
- Satellite observations: microwave, infrared hyperspectral (IASI), etc.

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GRUAN: Collocation

- 1. Collocation
- Orbits close to 00Z and 12Z
- IASI FOVs less than 25 km and 30 min apart from Manus
- With above criteria met, searched for IASI FOVs 500 km away



GRUAN: Pre-processing

2. Pre-processing

- No interpolation
- Humidity bias corrections for the Calculated radiances: GRUAN + 3% RH (most likely coming from RTM)

Cal/Val Strategy: Consistency check

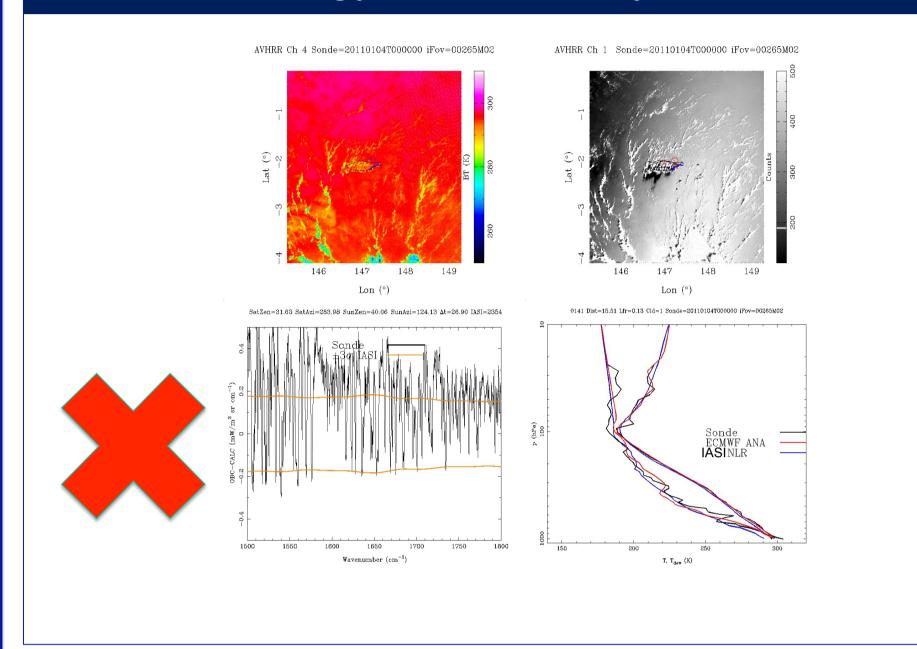
- 3. Consistency check
 - New proposed step which seems pivotal
 - · Observed IASI radiances (OBS) are compared to
 - Calculated radiances (CALC) using Sonde profile +
 Radiative Transfer Model (RTM)
 - · OBS-CALC should fall within ±3σ IASI instrument noise
 - · Necessary, but not sufficient condition!
 - Ideally not to be used as a further selection criteria!
 == Do not include in pre-processing, if possible.

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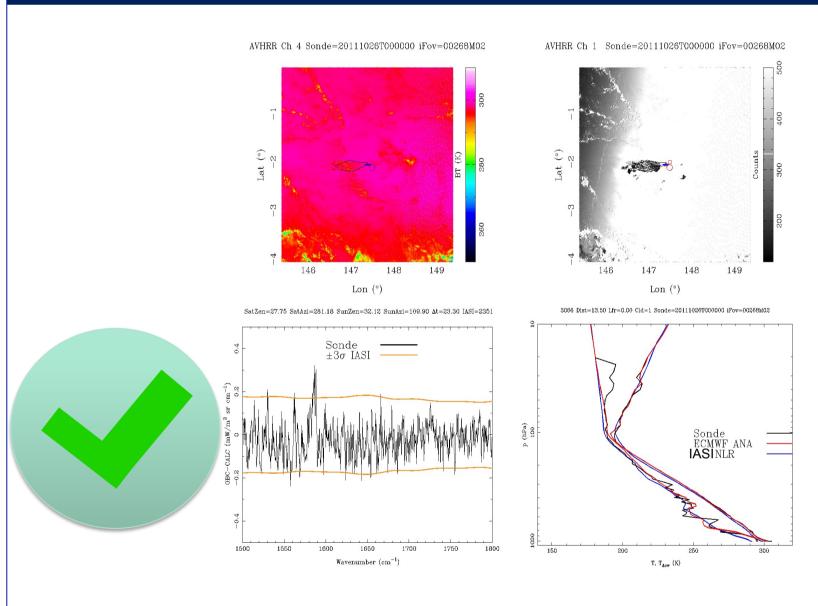
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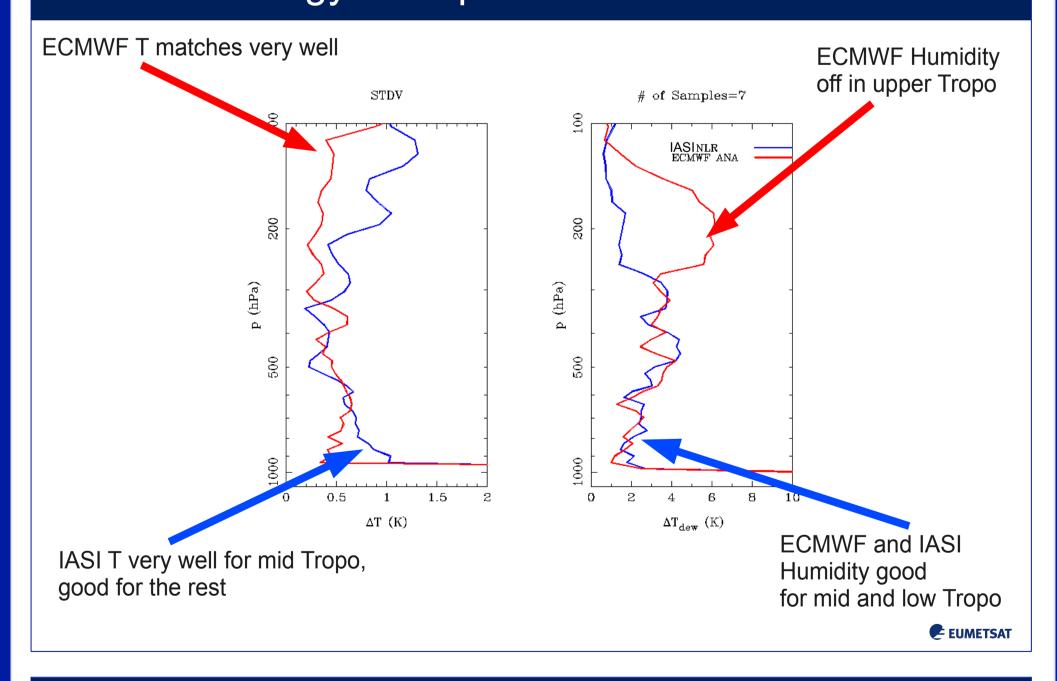
Cal/Val Strategy: Consistency check



Cal/Val Strategy: Consistency check



Cal/Val Strategy: Comparison: Profile Statistics



Other Examples

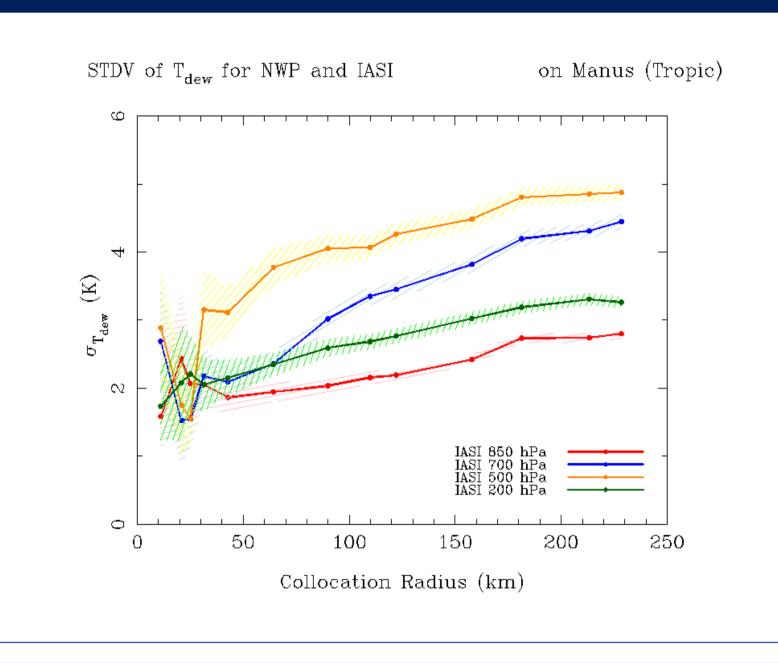
| Reference | Instruments | Collocati on | Pre- processing | Consistency check | Conclusion |
|-----------|--------------------------------------|--------------------------|--|---|---|
| Sodankylä | •RS92+CFH -1 hour •RS92 -5 min | 25 km 30 min | · · | •Passed 4 out of 4 | •Good measurement strategy and processing |
| SALSTICE | <i>J</i> 1 | 25 km 30 min | No interpol.Kivi RH bias correctionClear cases | Not all passed (~15/30) | •Needs further work |
| GRUAN | | 25 (500) km 30 min | No interpol.DirectGRUAN dataClear cases | •Passed 7 out of 8 | •Good measurement strategy and processing |

Dependency of Statistics with Collocation Radius

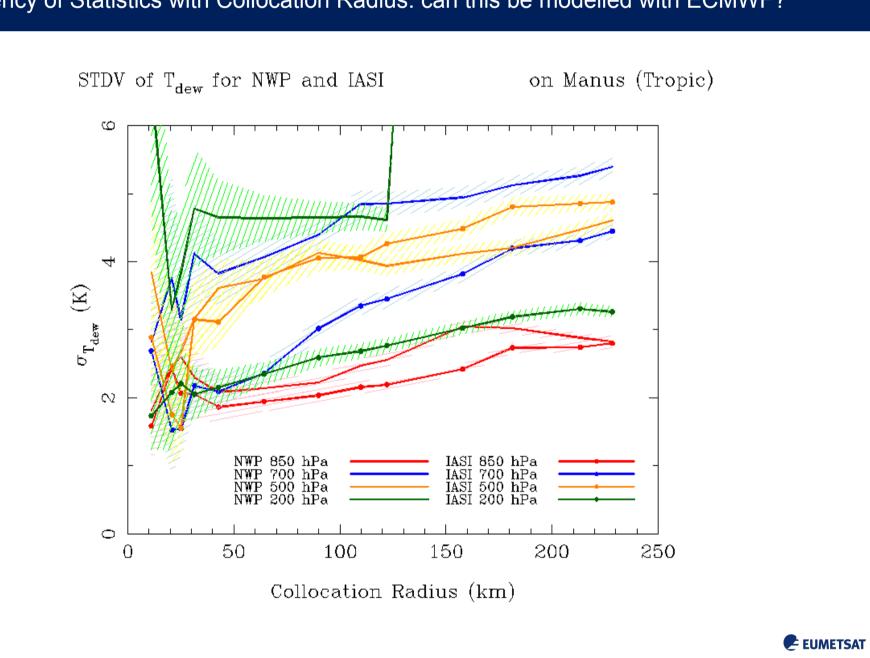
IASI: $H_{I}(x_{I})=H(x_{I})+\mu_{I}+\sigma_{I}$ GRUAN: $H_{S}(x_{S})=H(x_{S})+\mu_{S}+\sigma_{S}$

Validation: $\sigma^2(H_1-H_S) = \sigma^2_C + \sigma^2_1 + \sigma^2_S$

Dependency of Statistics with Collocation Radius

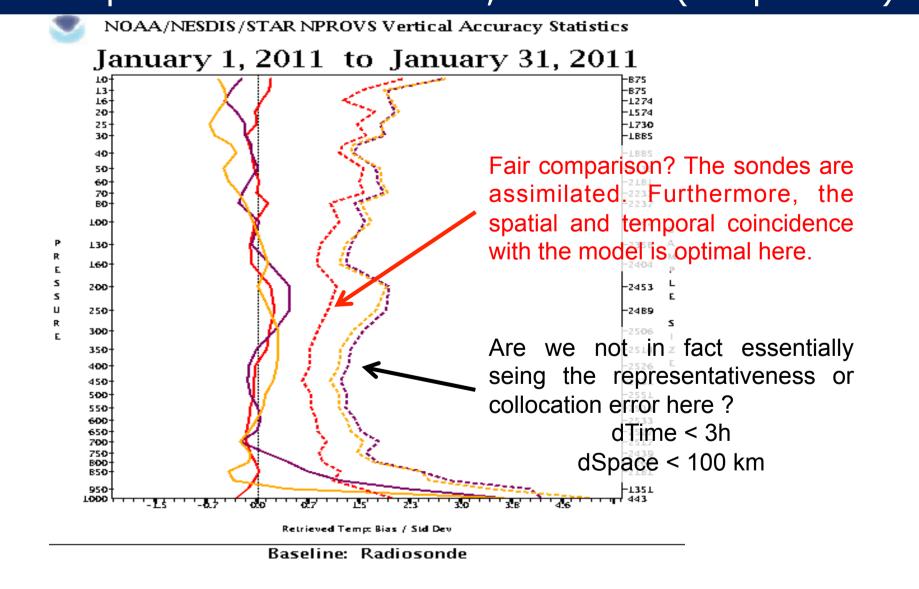


Dependency of Statistics with Collocation Radius: can this be modelled with ECMWF?



Collocation error?

A comparison Sondes vs model, vs IASI L2 (Temperature)



Credits: NOAA / NESDIS Center for Satellite Applications and

CONCLUSIONS

- Only Manus is well located with launches at 00 and 12 UTC to collocate well with IASI. Only 8 clear sky collocations in one year.
- GRUAN humidity needs to be corrected with RH+4%. An issue most likely from the RTM, but...?
- RTM issue with the Water Vapour Continuum?
- Consistency check reduces collocation errors to a minimum.
- For most atmospheric levels, the collocation error for humidity, in Manus, can be modelled with ECMWF.
- ECMWF humidity not accurate at 200 hPa in this region.
- More interaction possible between RTM, Sat and Sonde groups?

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