Recent development of satellite data assimilation at JMA

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Abstract

Recent developments in satellite data assimilation at JMA since the last TOVS conference in May 2008 a re presented. JMA i ntroduced v arious s atellite da ta i n the g lobal operational 4D-Var assimilation sy stem: S SMIS o f D MSP-F16 a nd -F17, N OAA19/AMSU-A a nd M HS, and Metop/ASCAT ocean surface wind and GRAS refractivity. Pre-processings of r adiance assimilation was unified and improved for the better maintainability and extensibility and for increasing accuracy of a nalysis. Bias co rrected radiances o f S SMIS i maging and t emperature so unding ch annels are comparable to corresponding channels of S SMI and AMSU-A i n quality and show slightly positive impacts on forecasts. Assimilation of clear sky radiances of AIRS and IASI reduces warm biases in the upper troposphere i n the low latitude but f urther de velopment is n eeded f or t he op erational implementation b ecause there is degradation in the lower tropospheric t emperature. The website is opened for real-time monitoring of radiances and AMVs: http://qc.kishou.go.jp/

1. Outline of JMA NWP system and satellite data (to be) assimilated

JMA o perates two d eterministic f orecast m odels: the g lobal s pectral m odel (GSM) and mesoscale model (MSM, Japan M eteorological A gency 2007). GSM provides short-range (1 - 2 days) and one-week forecast and aeronautical forecast, and runs every six hours. The resolution is TL959L60 (roughly 20 km in horizontal resolution) with model top height of 0.1 hPa. MSM provides the disaster prevention information such as heavy rain prediction around Japan. It is a non-hydrostatic grid model with a horizontal resolution of 5 km and 50 vertical layers up to about 22 km (Saito et al. 2006). MSM runs every t hree hour s a nd performs 15-h f orecast a t 00 /06/12/18 U TC a nd 33-h f orecast a t 03/09/15/21 UTC.

The global data a ssimilation s ystem is based on incremental 4D-Var with the r esolution of TL959L60/T159L60 in the outer/inner loop. 6-hour assimilation window is divided into six time slots of about 1-hour. Data cut-off times are 2h25m for the early analysis, and 5h35m and 11h35m for the cycle analysis at 00/12 UTC and 06/18 UTC, respectively. Variational Bias Correction (VarBC, Sato 2007; Ishibashi 2009) is applied for all radiance data.

The assimilation system of MSM was significantly upgraded f rom a hydrostatic-base t o a non-hydrostatic base in April 2010, where system components were fully investigated and renovated

including control variables and penalty term suitable for a non-hydrostatic model (Honda et al. 2005). The new MSM 4D-Var, or JNoVA (JMA N on-hydrostatic model based Variational data Assimilation system), has the resolution of 5/15 km in the outer/inner loop. Assimilation window is three hours with three 1-hour time slots and data cut-off time is 50 minutes. While the global 4D-Var system assimilates radiances from various satellites, JNoVA still assimilates retrievals such as temperature profiles from ATOVS and total co lumn w ater v apor (TCWV) f rom microwave i magers. The development of radiance assimilation in JNoVA is underway.

Satellite data operationally assimilated and to be assimilated in the global and meso-scale analysis systems are shown in Table 1 as of April 2010.

Table 1: Satellite data operationally assimilated in the global and meso-scale analysis				
systems as of April 2010. The table includes data under development of assimilation, depicted				
in parentheses.				

Satellite/Instrument		Global Analysis	Meso-scale Analysis
Sounder	NOAA15,16,18,19/AMSU-A	Radiance	Temperature , (\rightarrow Radiance)
	NOAA15,17,18,19/AMSU-B,M	Radiance	Temperature , ($ ightarrow$ Radiance)
	HS		
	Aqua/AMSU-A	Radiance	(Radiance)
	Metop/AMSU-A,MHS	Radiance	Temperature , (\rightarrow Radiance)
	DMSP16/SSMIS	Radiance	(Radiance)
	(Aqua/AIRS, Metop/IASI)	(Radiance)	(Radiance)
MW	TRMM/TMI	Radiance	TCWV(\rightarrow Radiance) , Rain Rate
Imager	Aqua/AMSR-E	Radiance	TCWV(→Radiance), Rain Rate
	DMSP16,17/SSMIS	Radiance	(TCWV(→Radiance), Rain Rate)
VIS/IR	MTSAT-1R, Meteosat-7,9,	Radiance	(Radiance)
Imager	GOES-11,12	AMV	AMV
	Aqua,Terra/MODIS	AMV	Х
Scattero	Metop/ASCAT	Ocean surface wind	(Ocean surface wind)
meter			
GPS-RO	GRACE	Refractivity	(Under development)
	Metop/GRAS	Refractivity	(Under development)
Ground-based GPS		(Zenith Total Delay)	TCWV (\rightarrow Zenith Total Delay)

2.1 Unify and improve pre-processings of radiance assimilation

JMA's o perational d ata a ssimilation sy stem consists of d ecoding, sh ort-range f orecast to create first-guess, obs ervation p re-processings, m ain an alysis and p ost-processings. The observation pre-processings include QC, thinning, a djusting of observation errors and b ias c orrection, and r un separately depending on data type. R adiance pre-processings had been d eveloped separately f or

sounders, clear sky radiances (CSRs) of geostationary satellite imagers and MW imagers despite using several same processing packages including RTTOV. Since this separate development had harmed the maintainability of source codes and extensibility to the new instruments, the unified pre-processings of radiance ass imilation were created. In a ddition, i mprovements of pr e-processing w ere m ade (Kazumori 2009a): First, cloud screening QC was made stricter for MW imagers by changing rejection criterion of total column cloud liquid water (TCCLW) from 0.18 k g/m² to 0.1 k g/m². In order to remove residual cloud effect on radiance, TCCLW was added as a VarBC predictor. Second, using ATOVS p ixels a t bo the dge scan positions was resumed because t heir O -B st atistics were n ot profoundly different from t hose a t i nner p ositions. Finally R TTOV-8.7 w as i ntroduced in b oth pre-processing and main analysis i nstead of R TTOV-7. The improved pr e-processings resulted in making fewer but more reliable MW imager data available, increasing ATOVS data and more accurate estimation o f MW o cean su rface emissivity. C ycle ex periments including t he new r adiance assimilation pre-processings and using RTTOV-8.7 in the main analysis showed a clear improvement of tropospheric humidity analysis by reducing model dry bias. Forecast of tropospheric temperature and geopotential height, especially over the ocean in the Tropics and S.H., were improved. The new radiance pre-processings and the introduction of RTTOV-8.7 became operational in October 2008.

Furthermore, the latest version of RTTOV (version 9.3, Saunders et al. 2008) was introduced in the operational global data assimilation system in March 2009 (Kazumori 2009b). In our cycle experiment to asses impacts of using RTTOV9.3 relative to using RTTOV8.7, stratospheric temperature forecasts were significantly improved verified against their own analyses (left panel of Fig. 1) and GPS-radio occultation (RO) r etrievals (right p anel of Fig. 1). This improvement is cau sed by better J acobian mapping f rom a ne wly introduced vertical interpolation a lgorithm (Rochon e t. al. 2007) and by discontinuing invalid Zeeman effect (Kobayashi et.al. 2009).

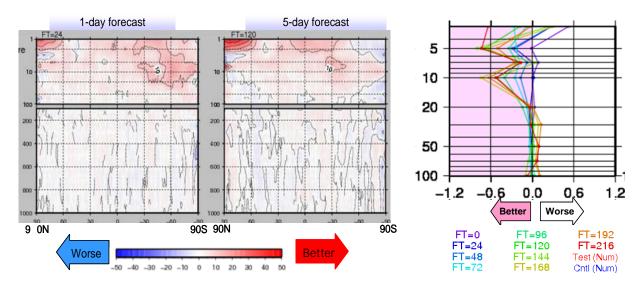


Figure 1: (left) Monthly zonal mean of forecast improvement rate for temperature in September 2008. The improvement rate is defined as normalized root mean square of forecast error difference and positive values indicate smaller forecast errors. (right) Difference of standard deviation for temperature forecast in the N.H. verified against GPS-RO

2.2 SSMIS radiance assimilation

JMA has been assimilating clear radiances of MW imagers in the global data assimilation since May 2005 (Okamoto et al. 2008). We have been receiving S SMIS SDR of DM SP-F16 and -F17 from NESDIS and U KMO v ia ftp. Although SSMIS suffers calibration a nomaly of unexpectedly large emissivity of r eflector and w arm l oad c ontamination by s unlight, t hese or ganizations have been developed correction algorithms and providing corrected data. It was found that the quality of most channels of SSMIS are comparable to that of corresponding channels of SSMI and AMSU-A after QC and bias correction (Fig. 2). Thus, we assimilate clear radiances of SSMIS imaging and temperature sounding channels in a similar way to SSMI and AMSU-A, respectively.

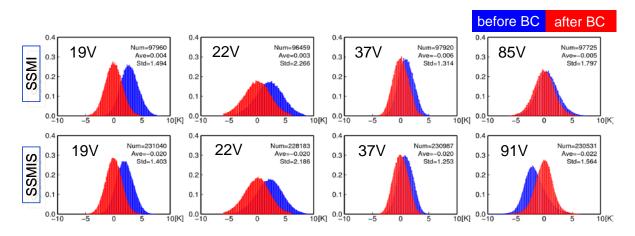


Figure 2: Frequency distribution and statistics for the O-B of brightness temperature before/after bias correction.

For imaging channels of SSMIS, channels 13, 14, 16 and 17 (19V, 22V, 37V and 92V) are assimilated over the ocean. The same pre-processings as other MW imagers (Okamoto et al. 2008) are applied for SSMIS: (1) removing cloud affected pixels using cloud indices and TCCLW criteria (see the Section 2.1), (2) gross error QCs for O-B with respect to brightness temperatures and TCWV retrievals, (3) thinning to one pixel in a 200 k m box, (4) inflating observation e rrors (four t imes l arger than predefined e rror v alues e stimated f rom O -B s tandard de viation), and (5) correcting b iases u sing a linear regression approach whose coefficients are given by the previous analysis with VarBC. Impacts of the addition of S SMIS imaging channel r adiances on the analysis and forecast were small and neutral. Assimilating TCWV and rain rate retrievals in JNoVA, as is done for other MW imagers, is under development.

For t emperature s ounding c hannels of S SMIS, tropospheric c hannels 2, 3, 4 and 5 are assimilated. Channels 6, 7 and 24 are removed due to large bias inconsistency on a scending/descending or bits. Channels 21, 22 and 23 are not used because they are sensitive to temperature above the model top. A scan line QC, which removes data whose scan lines are erroneously located, is added to AMSU-AQC procedures such as cloud and gross-error QCs (Okamoto et al. 2006). Larger observation error (1.0 K) and smaller thinning distance (160 km) than AMSU-A (0.4 K and 250 km, respectively) are assigned. Two 50-days cycle experiments in September 2008 and January 2009 s howed the addition of those temperature so unding channels of D MSP-F16/SSMIS s lightly improved data coverage and yielded positive impact on short-range forecasts of Z 500 in the S.H. More d etails about assimilating the imaging a nd s ounding channels of S SMIS can be found in Egawa (2010) and Kazumori (2009c), respectively.

2.3 AIRS & IASI clear radiance assimilation

The assimilation of clear radiances of the hyperspectral infrared sounders of AIRS and IASI has been developed. We have been receiving AIRS 324 channel data at warmest FOVs from NASA and IASI 616 channel data at all FOVs from NESDIS via ftp. The current target of assimilation is radiances sensitive to the stratospheric and tropospheric temperature in the CO2 15 µm and 4.3 µm bands. Channels affected by ozone or minor gases, the surface and the atmosphere above the model top are rejected. Shortwave infrared channels of IASI are removed because of large instrumental errors. As the first st ep o f a ssimilation development, h umidity sensitive channels are n ot i ncluded b ecause of relatively difficult usage in that their high nonlinearity and humidity biases of our forecast model may deteriorate analysis. A mong remaining channels, channels with higher priority are selected u sing a measure of an entropy reduction (ER, Rogers 2000; Rabier et all 2002). Because it is found that both ER and reduction o f an alysis e rror b ased on a MA P an alysis does not d iffer so m uch by adding channels over 100 channels, 82 channels of AIRS and 74 channel of IASI are used. We are planning, as a next step of development, that additional channels will be used in order to extract the humidity and lower tropospheric information.

Channels affected by clouds are identified and removed using cloud top height (CTH) determined by a

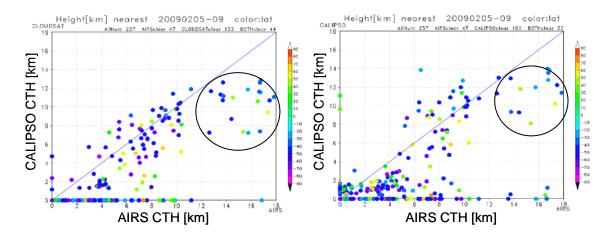


Figure 3: Comparison of AIRS cloud top height (CTH) with those from CloudSat (left) and CALIPSO (right) from 5 through 9 February 2009. CloudSat and CALIPSO CTHs are taken from 2B-GEOPROF and 2B-GEOPROF-LIDAR data set, respectively, and matchup criteria are 5 km from the center of AIRS FOV and 20 minutes.

CO2 s licing method. T he method of ten f ails t o identify CTH for small clouds or positive O-B of reference channels. In these cases, clear detection algorithms are applied based on cloud flag derived from the VIS/NIR i mager of A IRS and AVHRR cloud a nalysis collocated with IASIF OV, a nd comparison of JMA 's S ST an alysis with S ST retrieval from A IRS or I ASI obs ervation. P lease note that the clear detection uses no atmospheric background information w hile the CO2-slicing method uses it, indicating the latter can be affected by model bi ases and dependent on the performance o f the cu rrent O -B b ased bias correction procedure. If C O2-slicing fails but the clear detection algorithm declare clear, the pixel is flagged as cl ear. If bot h C O2-slicing an d cl ear detection fail, it is assumed that clouds are located

at the tropopause. This assumption may cause w rong ass ignment o f excessively h igh C TH t o so me clouds and remove some channels that would be used if correct CTH is given. This feature is somewhat confirmed from comparisons with CloudSat and CALIPSO (circles of Fig. 3). This is, however, safer than vice versa because it prevents cloud-contaminated channels from wrongly used. Figure 3 shows that CTH f rom A IRS agrees w ith CloudSat a nd C ALIPSO w ithin 1-2 km but A IRS ov erestimates CTH f or hi gh c louds, d escribed above, and identifies clouds where CloudSat a nd C ALIPSO do not, probably because o f d ifferent FOV sizes.

Removing b iases o f brightness temperature is c rucial n ot o nly

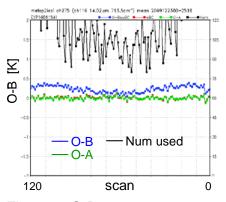


Figure 4: O-B mean vs. scan position for IASI channel 275 from 23 through 25 December 2008. Mean observation-minus-analysis (O-A) and number used also plotted in green and black line.

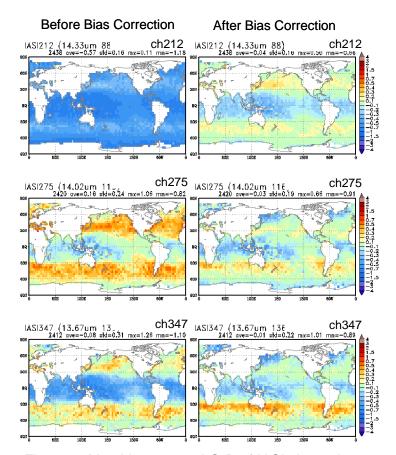


Figure 5: Monthly averaged O-B of IASI channels 212, 275 and 347 before (left column) and after (right column) bias correction. The average is taken from 1 through 31 January 2009.

because variational assimilation assumes there are no biases in observations used but also because bias corrected O-B is used in QC and cloud detection of CO2 slicing method. VarBC is applied for both AIRS and IASI with the predictors of normalized brightness temperature calculated from first-guess, nadir view angle raised to one, two, three and four, and constant. Adding the fourth-order term, unlike Collard and McNally (2009), is based on the variation of O-B of channels sensitive to lower tropospheric temperature with nadir view angle (blue line in Fig. 4). Figure 5 shows monthly averaged O-B be fore and a fter the bias correction for channels 212, 275 a nd 347 of IASI, s ensitive to the stratospheric t emperature, upper tropospheric temperature a nd m id-tropospheric temperature, respectively. The biases for these channels are reduced after the bias correction but still remains in the low latitudes for all of these channels (negative b iases) and the latitude band of 30 -50S for the tropospheric channels (positive biases). We suppose that most of these remaining biases results from model biases, shown in Fig. 6, but cannot deny the possibility of deficiencies of cloud detection and bias correction procedures. The validation of these procedures is still underway.

Cycle experiments to assess IASI and AIRS assimilation has been conducted for 20 December 2008 through 9 February 2009 ("Jan2009" experiment) and 20 July through 9 September 2009 ("Aug2009" experiment) using a low-resolution suite of the operational global data assimilation system. Monthly average of zonal mean temperature difference in the right panel of Fig. 6 shows the IASI and AIRS assimilation c ools t he u pper t roposphere a round 200 hP a i n t he l ow latitude a nd w arms mid-troposphere in the 30-60 degrees in the S.H., reflecting Fig. 5. Compared with the 3-day forecast temperature error shown in the left panel of Fig. 6, this analysis difference demonstrates that the AIRS and IASI assimilation successfully reduces model biases. This favorable impact is also found in much better fitting t o r adiosonde t emperature at 200 hPa and is k ept until 2 -day forecast. H owever, the cooling of lower troposphere in the mid-latitude in the summer hemisphere seems to be excessive and does n ot agree with E CMWF an alysis (not s hown). We have found from s ensitivity te sts that the cooling d oes not r esult from obs ervation t hemselves nor ba ckground e rror covariance. Thus, we

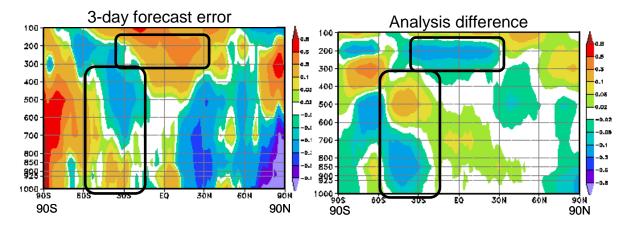


Figure 6: Monthly averaged zonal mean temperature in January 2008. (Left) 3-day forecast error against initial state. (Right) analysis difference by assimilating the AIRS and IASI radiance.

suppose that it is related to some model processes. The IASI and AIRS assimilation slightly increases moisture in the analysis, being in better agreement with AMSR-E r etrievals. Forecast s cores show seasonal and field dependency: MSLP improved in both Jan2009 and Aug2009 experiments but T850 and wind speed at 250hPa degraded in Jan2009 experiment. We are investigating the cause of these degradations, including t he e ffect o f c loud m issed, r emaining bi ases, interaction among c loud detection, QC and b ias correction, and model r esponse t o the analysis field modified by AIRS and IASI.

3. Plans

JMA has been steadily introducing new satellites and improving processings in the operational data assimilation sy stems. However, there a re significant developments needed including r adiance assimilation of hyperspectral sounders in the global analysis. A lso, replacing r etrieval a ssimilation with radiance assimilation is important issue. Preliminary results that assimilating radiances instead of temperature retrievals from AMSU-A are encouraging (Kazumori 2010) while there are issues peculior to regional assimilation systems: implementing VarBC where data available are highly variable in each analysis and limited channels used due to low model top.

Other developments with radiance assimilation in the global analysis are assimilating cloudy/rainy radiances and utilizing more data over land by introducing better land emissivity estimate. Moreover, optimizing obs ervation e rror covariance m atrices and b uilding an o bservation i mpact es timation scheme are underway (Ishibashi 2010).

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