

# Use of Radiances in the CNMCA Operational Ensemble Data Assimilation System

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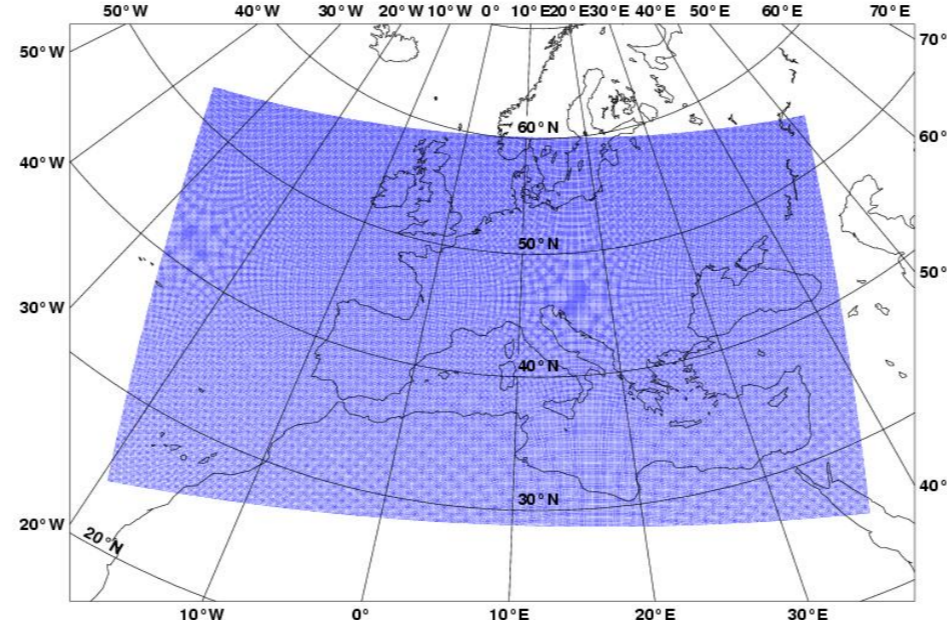


**CNMCA Implementation** (Bonavita, Torrisi and Marcucci, Q.J.R.M.S., 2008, 2010)

- **OPERATIONAL SINCE 1 JUNE 2011**
- **LETKF Formulation** (Hunt et al, 2007)

$$\begin{aligned} \text{Analysis Ensemble Mean } \bar{x}^a &= \bar{x}^b + X^b \bar{w}^a & \bar{w}^a &= \tilde{P}^a Y^b T R^{-1} (y - H(\bar{x}^b)) & \tilde{P}^a &= [(m-1)I + Y^b T R^{-1} Y^b]^{-1} \\ \text{Analysis Ensemble Perturb. } X^a &= X^b W^a & W^a &= [(m-1)\tilde{P}^a] & Y^b &= [H(x_1^b) - \bar{H}(\bar{x}^b), \dots, H(x_m^b) - \bar{H}(\bar{x}^b)] \end{aligned}$$

- 6-hourly assimilation cycle
- 40 ensemble members + control run with 0.09° (~10Km) grid spacing (HRM model), 40 hybrid p-sigma vertical levels (top at 10 hPa)
- (T,u,v,qv,ps) set of control variables
- Observations: RAOB, SYNOP, SHIP, BUOY, AIREP, AMDAR, ACAR, AMV (MSG), WindPROF, SCATwinds (ERS2, METOP), AMSUA radiances (since April 2012)

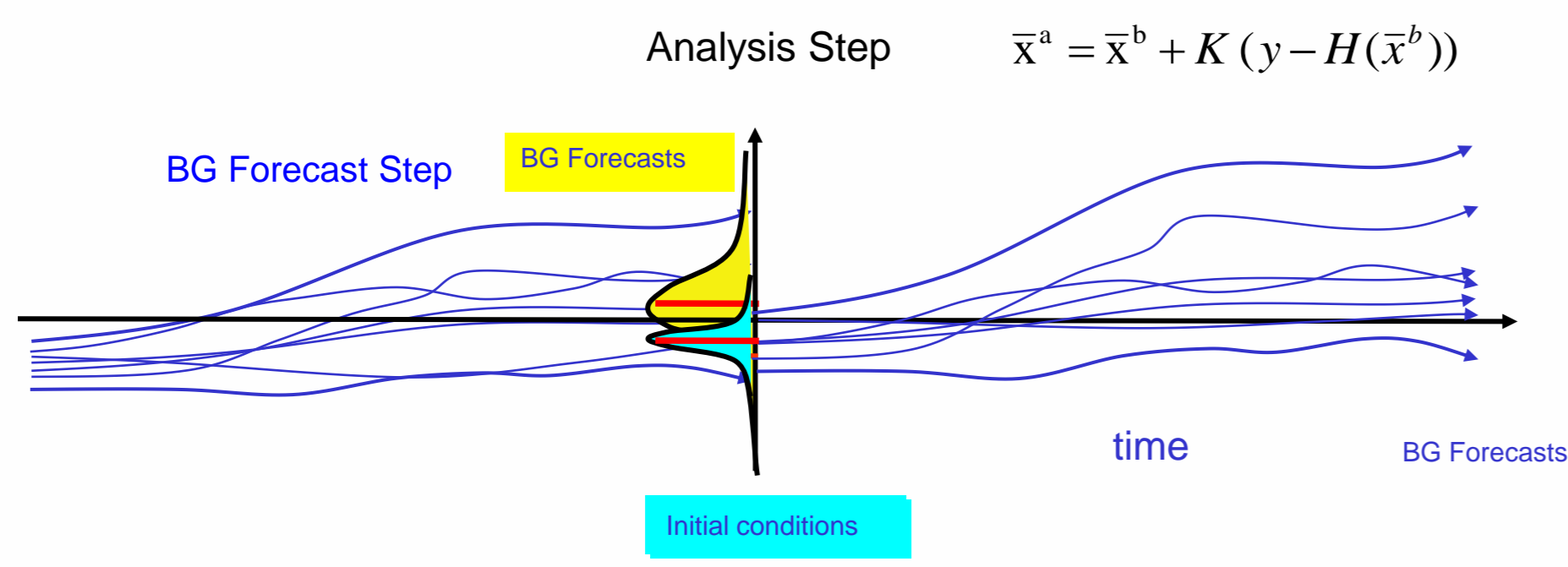


Model and sampling errors are taken into account using:

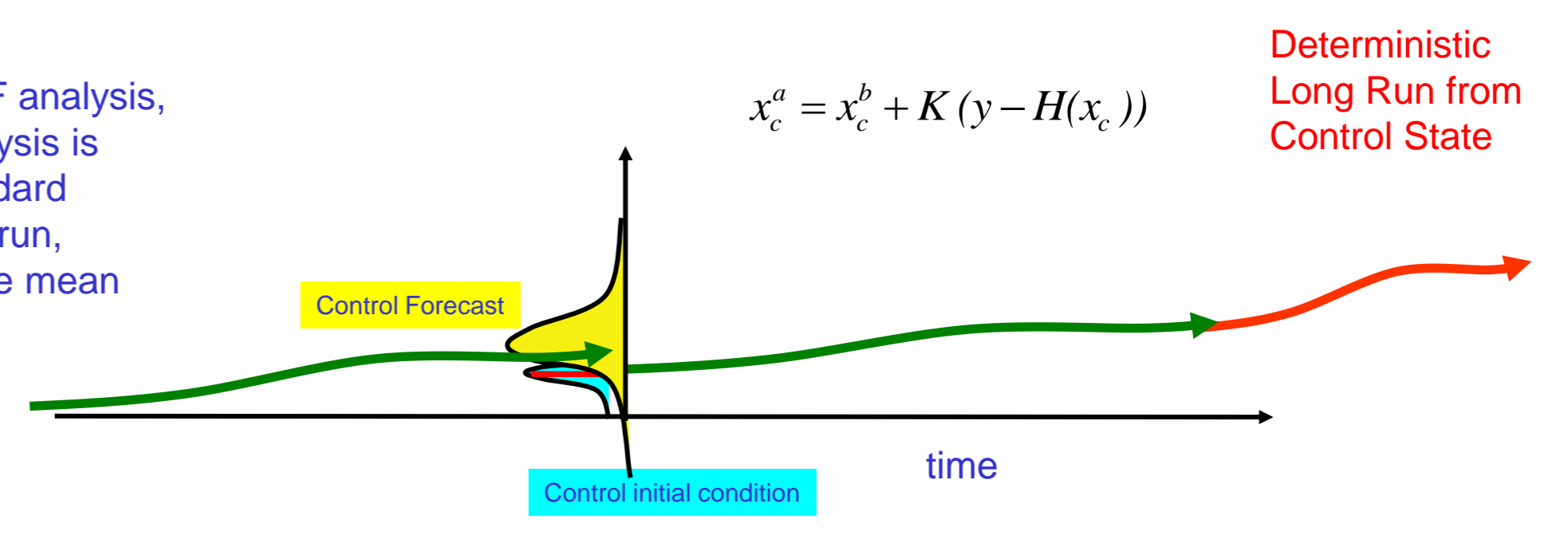
- State Dependent Multiplicative Inflation according to Whitaker et al (2010)
 
$$\text{an. pert. } x'_a = x'_a \sqrt{\alpha \frac{\sigma_b^2 - \sigma_a^2}{\sigma_a^2} + 1} \quad \alpha = 0.95 \quad \sigma^2 = \text{variance}$$
- Climatological Additive Noise
 
$$\text{an. memb. } x_i^a \leftarrow x_i^a + \alpha x_i^n, \quad \alpha x_i^n \sim N(0, Q) \quad \alpha \text{ Scale factor}$$

$x_i^n$  randomly selected, 48-24h forecast differences
- Lateral Boundary Condition Perturbation using EPS
- Climatological Perturbed SST

## Long Deterministic Run from LETKF

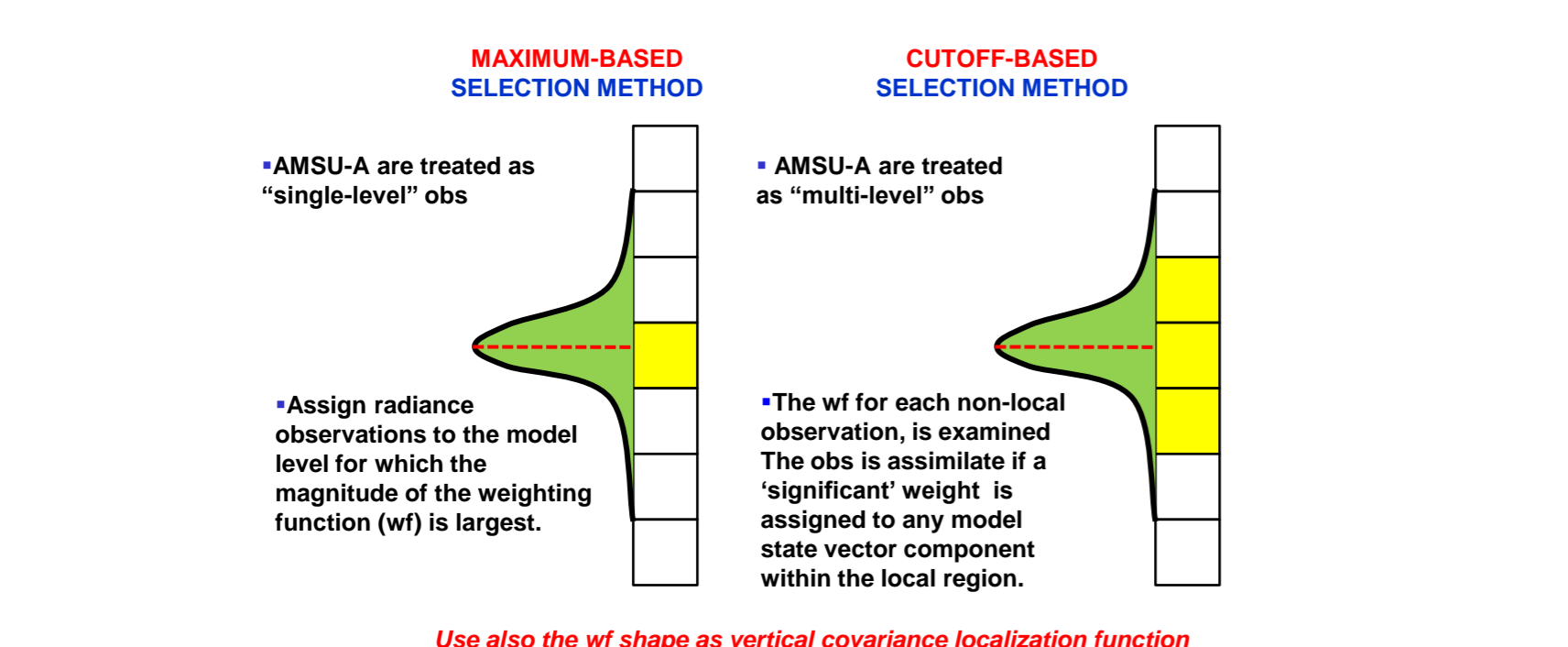
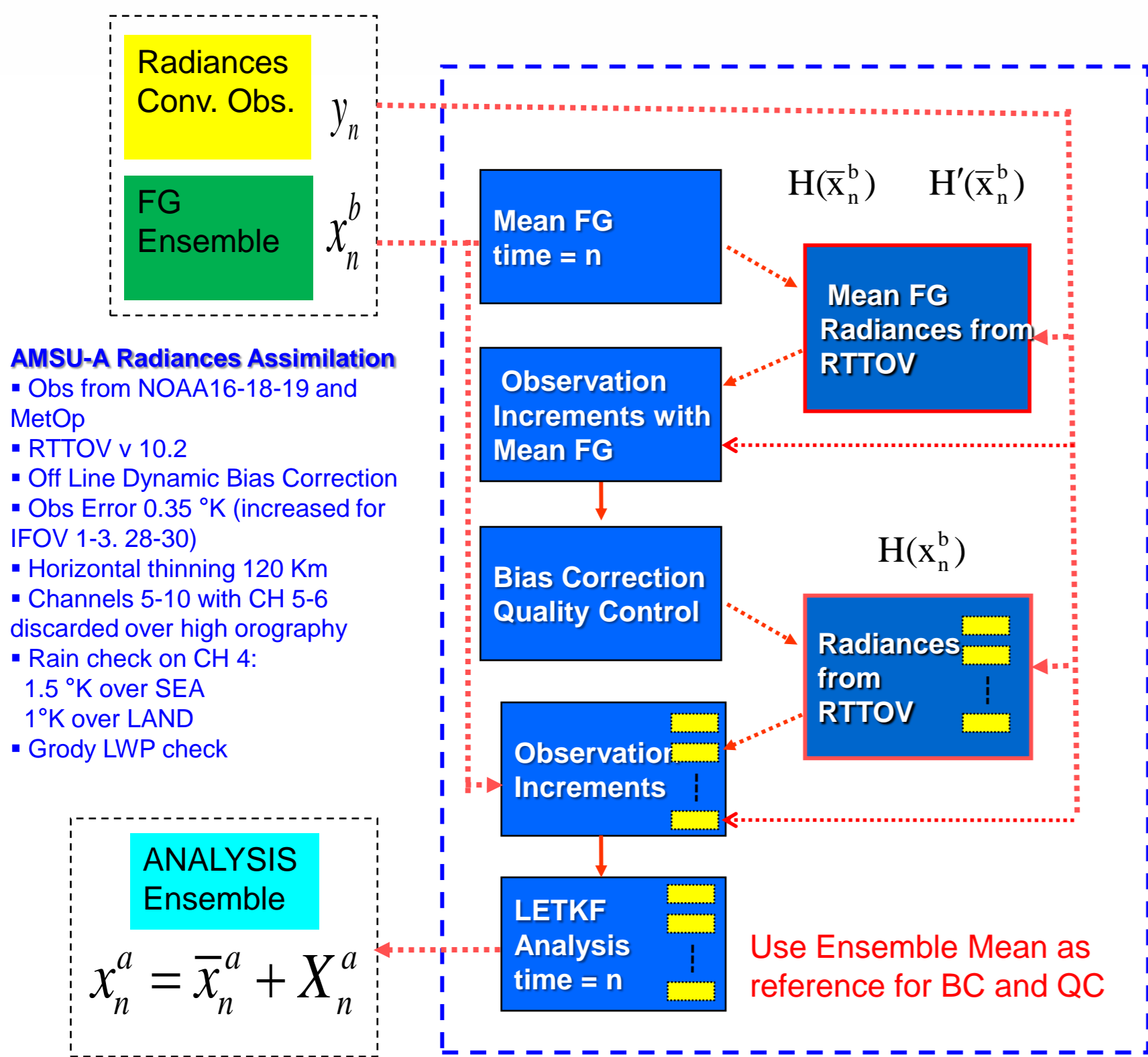


Along with standard LETKF analysis, a control state LETKF analysis is computed. It uses the standard Kalman gain and a control run, instead of the BG ensemble mean

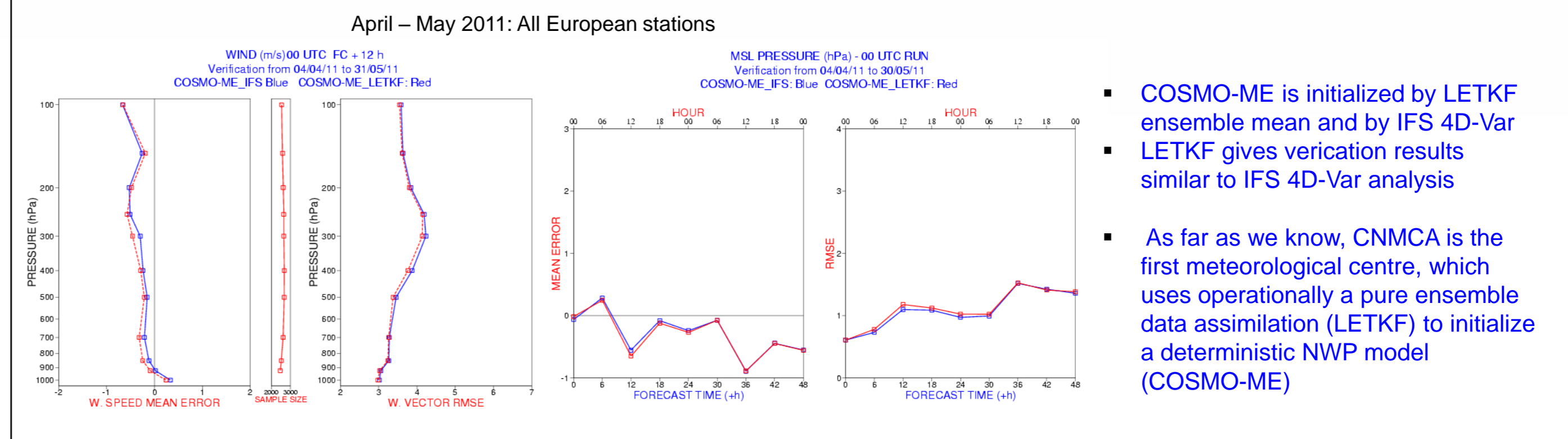


The use of a control state improves the first forecast hours with respect to the mean state (small scales filtered out)

## Radiances Assimilation Scheme



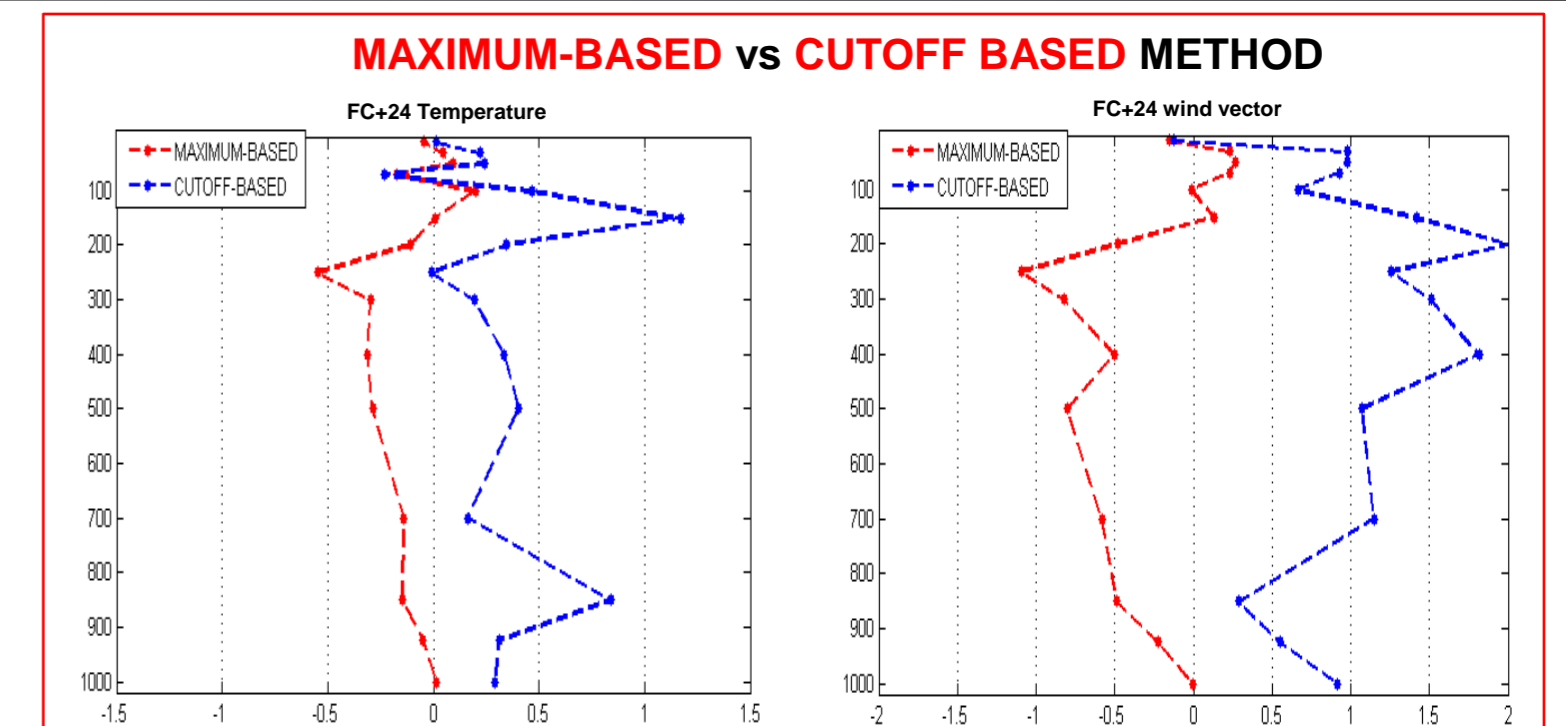
## LETKF vs IFS 4D-VAR Analysis



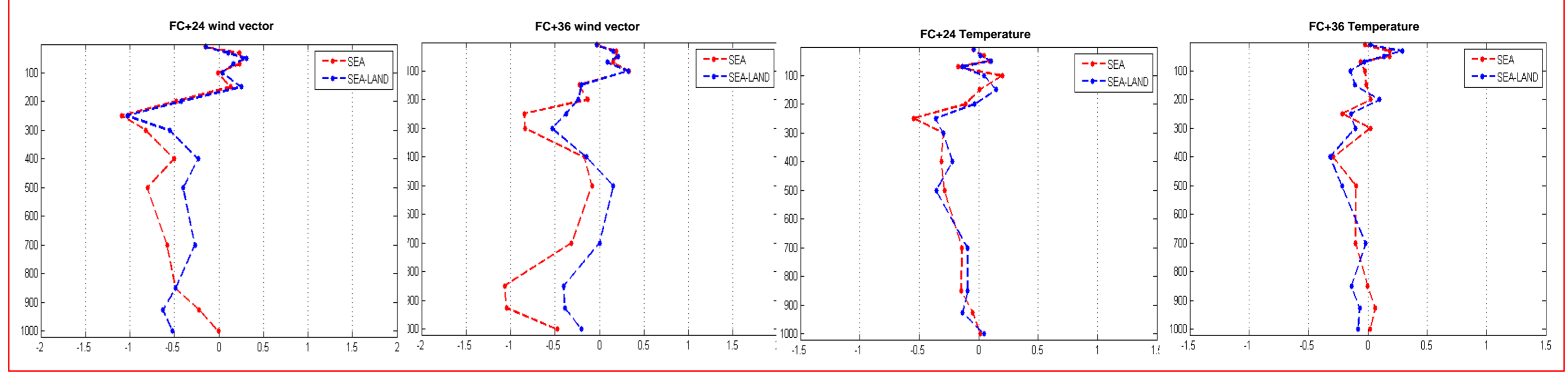
### EXPERIMENTS DESCRIPTION:

- ❖ Control run without AMSU-A assimilation
- ❖ Run with AMSU-A assimilated over SEA (MAXIMUM-BASED Method)
- ❖ Run with AMSU-A assimilated over SEA and LAND (MAXIMUM-BASED Method)
- ❖ Run with AMSU-A assimilated over SEA (CUTOFF-BASED Method)

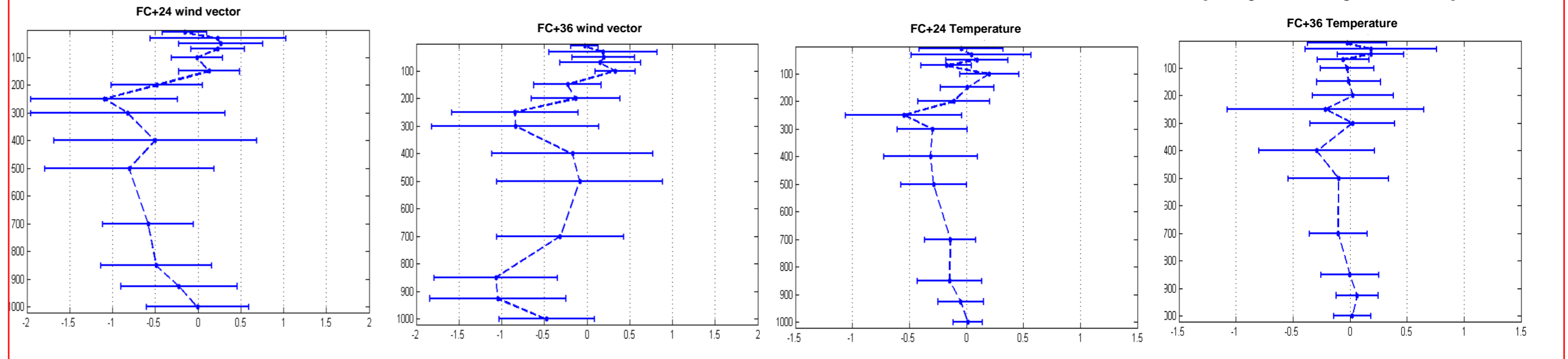
The vertical profiles of the relative rmse with respect to control run are shown



### MAXIMUM-BASED METHOD: SEA VS SEA-LAND AMSU-A ASSIMILATION (27 jun-18 jul 2011)



### MAXIMUM-BASED METHOD: AMSU-A ASSIMILATION OVER SEA (27 jun-18 jul 2011)



## FUTURE DEVELOPMENTS:

- Assimilation of AMSU-B/MHS and IASI retrievals will be investigated soon.
- Balancing and non-linearities are issues to address
- Tests with COSMO model and shorter assimilation window
- Further tuning of model error representation (tuning of cov. localization, evolved additive noise, bias correction, etc.)
- Implement a Short-Range EPS based on LETKF