Combining GPS occultations with AIRS infrared measurements for improved atmospheric sounding

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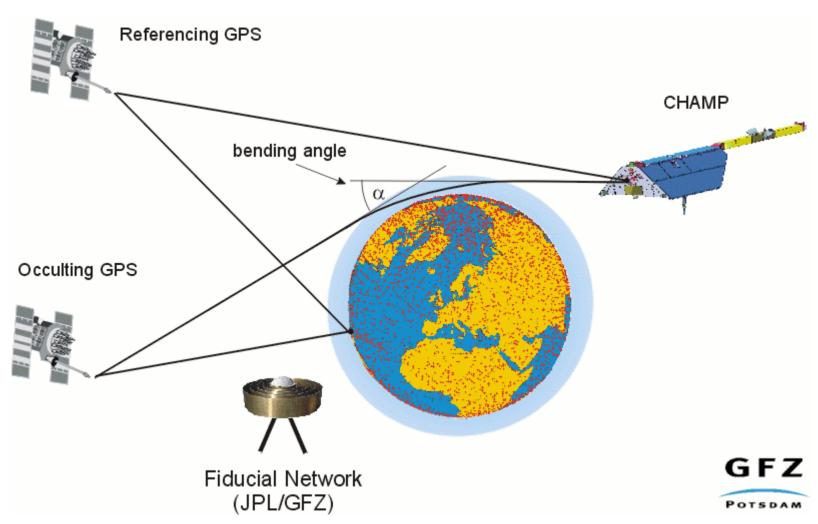
Outline

- Introduction Motivation, Reminder
- Input data
- Combined retrieval method
- Results
- Conclusion & Future Plans





Geometry of radio occultation









Motivation

GPS/RO

- –good absolute accuracy
- -very high vertical resolution, poor horizontal resolution
- -information in upper troposphere and stratosphere
- -high accuracy around tropopause
- -"all weather" instrument

IR and MW (ATOVS)

- -high horizontal resolution, poor vertical resolution
- -information from the total atmospheric column
- -more information on lower tropospheric temperature
- -less information around the tropopause

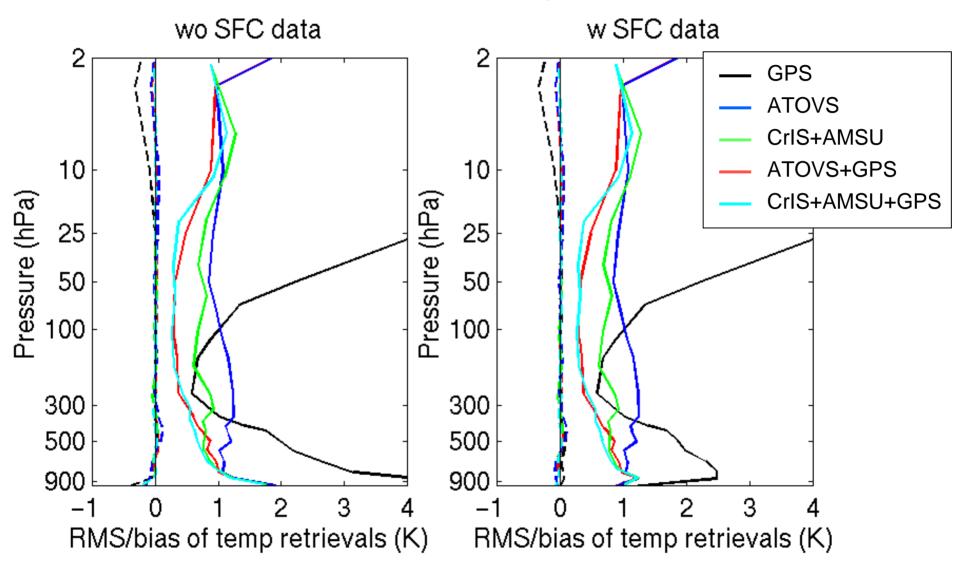
Results of simulation study

Results of real ATOVS+CHAMP/SACC study





RMS/bias diff of simulated temp retrievals from various systems

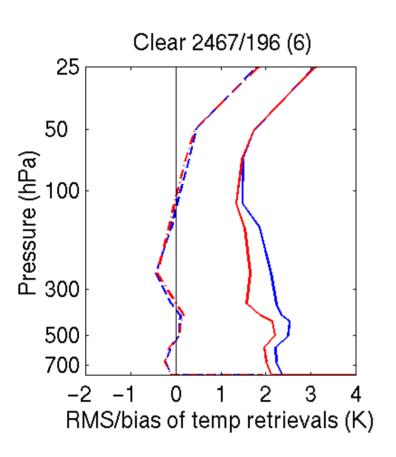


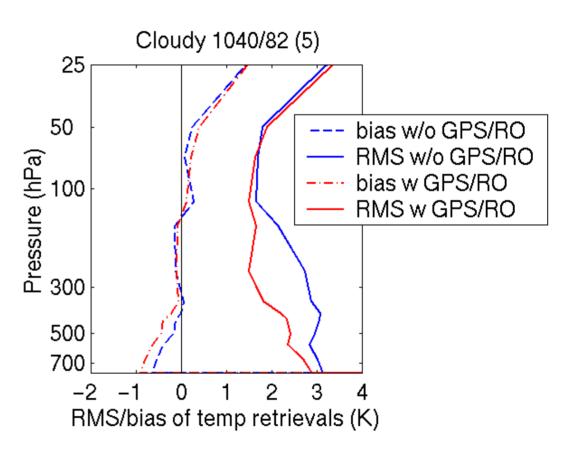




RAOB validation of SACC + ATOVS T(p)

Oct 2001, Jan, Apr and July 2002





GPS/RO (SACC) data improves the radiometric (ATOVS) temp retrievals around the tropopause by 0.5 K (larger impact over the cloudy skies)





Input data

Time period: Sept 2002 – Oct 2003

AIRS+RAOB matchup (100,266 collocations)

GPS data (SAC-C) July 2001 and Dec 2003: 66,989 occultations

GPS data (CHAMP) May 2001 and Dec 2003: 106,609 occultations

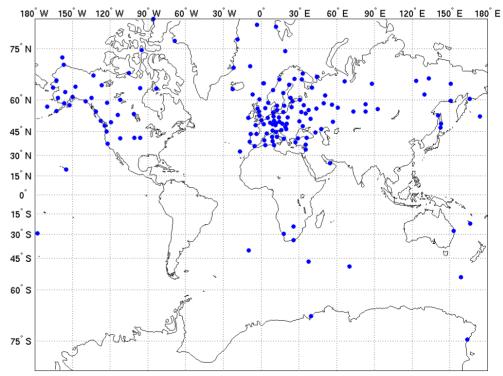
AIRS+RAOB+GPS collocation:

1980 (382 clear sky)

AMSU (AQUA): v3.0.8.0

AIRS level 2: v3.0.8.0





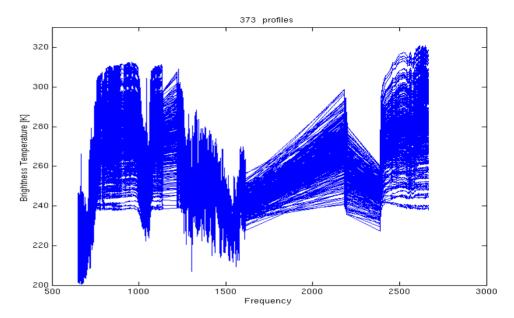
Location of AIRS+AMSU+RAOB+GPS collocations



Method

Test of different cloud masks:

Clear: if BT(obs) –BT(calc) <= 7 for less than 10 selected channels



Test of different set of selected channels and retireval methods:

Clear sky PC statistical regression method number of PCs:30

6 BT and 11 scan angle classification with 1688 selected channels

Class	BT@1000 cm ⁻¹ training	BT@1000 cm ⁻¹ observations
1	BT ≤ 260	BT ≤ 255
2	250 <bt≤270< td=""><td>255<bt≤265< td=""></bt≤265<></td></bt≤270<>	255 <bt≤265< td=""></bt≤265<>
3	260 <bt≤280< td=""><td>265<bt≤275< td=""></bt≤275<></td></bt≤280<>	265 <bt≤275< td=""></bt≤275<>
4	270 <bt≤290< td=""><td>275<bt≤285< td=""></bt≤285<></td></bt≤290<>	275 <bt≤285< td=""></bt≤285<>
5	280 <bt≤300< td=""><td>285<bt≤295< td=""></bt≤295<></td></bt≤300<>	285 <bt≤295< td=""></bt≤295<>
6	290 < BT	295 < BT





AIRS+AMSU+GPS Clear Sky retrieval

Regression Retrieval of T, q, O3, Ts, Ps, and ε_s under clear conditions

Regression Model

$$X = C Y$$

Least squares regression solution

$$C = X Y^{T} (Y Y^{T})^{-1}$$

X...Atmospheric State,

C...Coefficients,

Y...Measurements: AIRS & AMSU BTs and GPS refractivity profiles

Forward Model Calculations

AIRS BTs: SARTA model

AMSU BTs: Paul van Delst's implementation of Liebe MPM line-by-line model (Channels: 6-14)

GPS refractivity profiles: (Healy & Eyre, 2000) with vertically correlated measurements errors (200m vertical resolution)





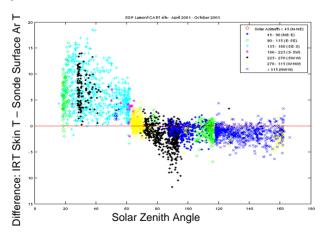
POSTER !!!!!

Training Data

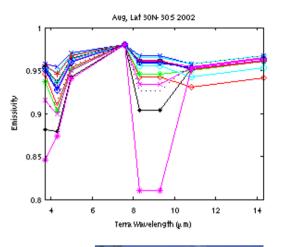
- •12,245 global atmospheric profiles
- •Profiles are taken from the NOAA-88, ECMWF training set, TIGR-3, ozonesondes, desert radiosondes
- All with saturation checks and other QC
- New Surface Skin Temperature assigned to profiles

New ecosystem-based Surface Emissivity assigned

to profiles





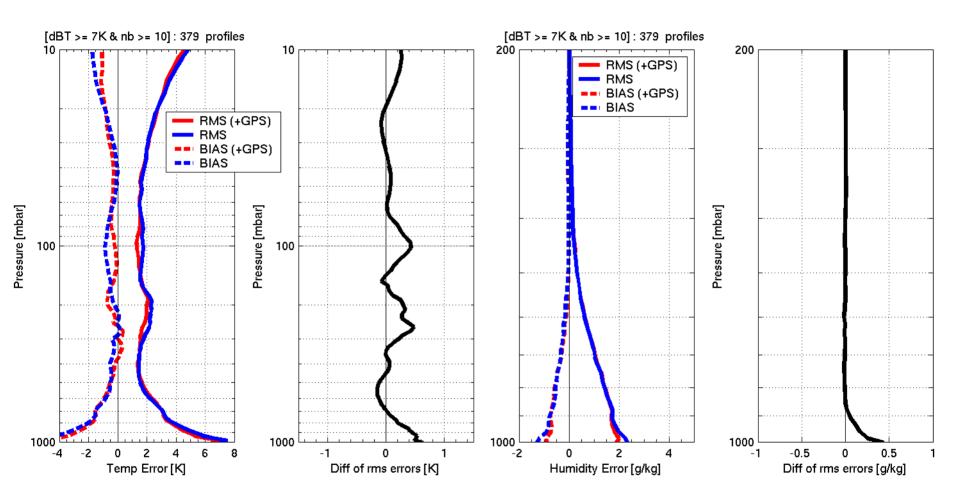








RAOB validation of AIRS+AMSU retrievals with and without GPS data

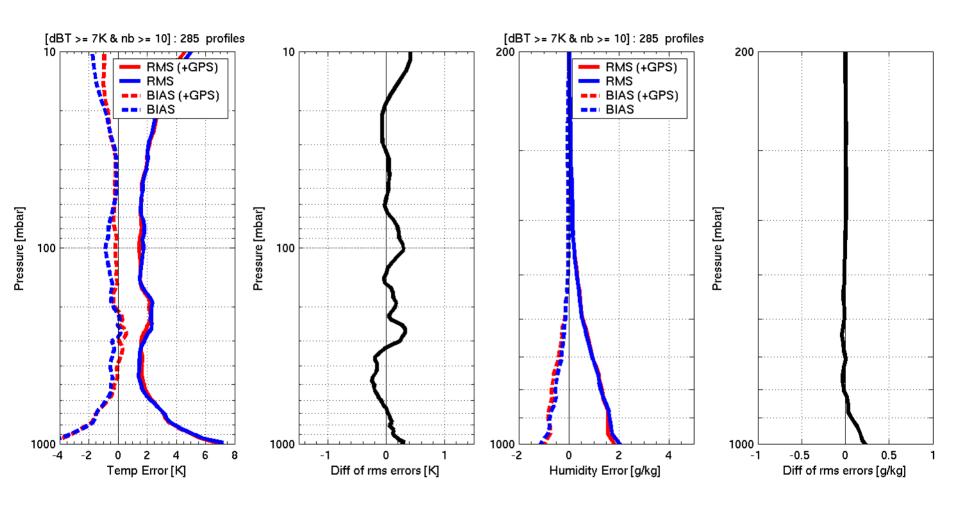


GPS between 8 and 26 km





RAOB validation of AIRS+AMSU retrievals with and without GPS data

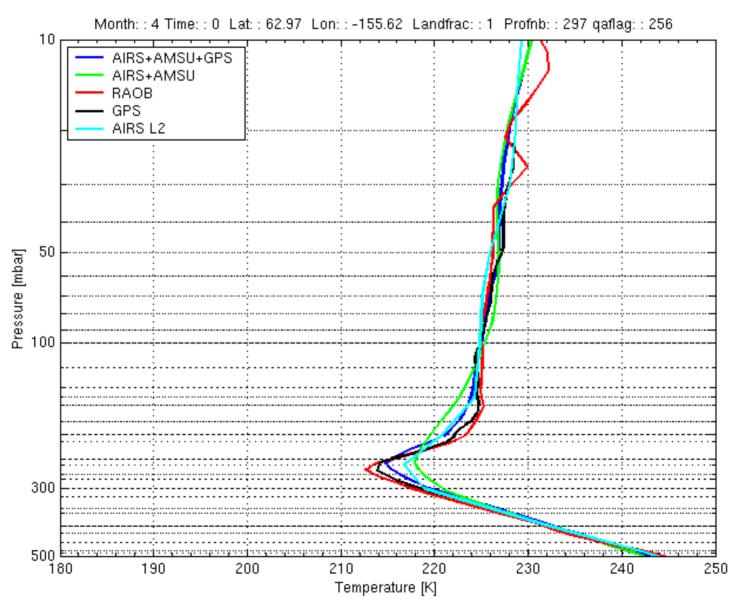


GPS between 1 and 26 km (3Xσ3Xnoise)





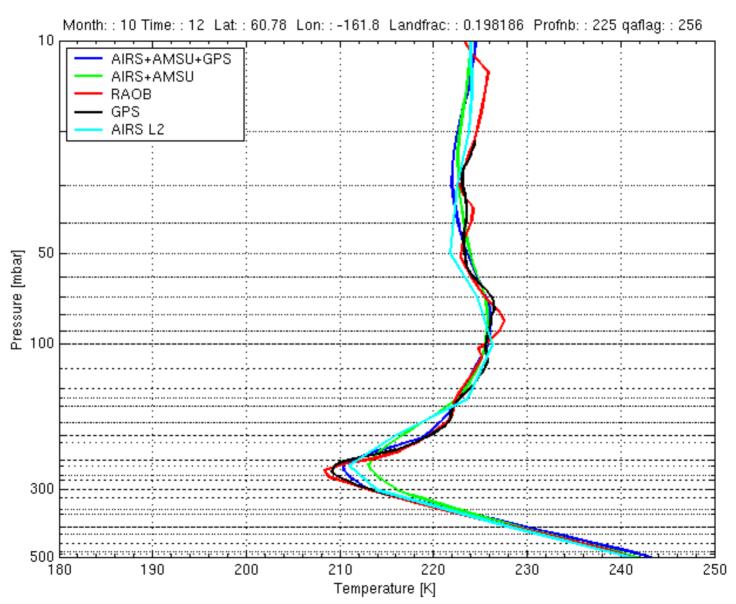
Comparison of temperature profiles







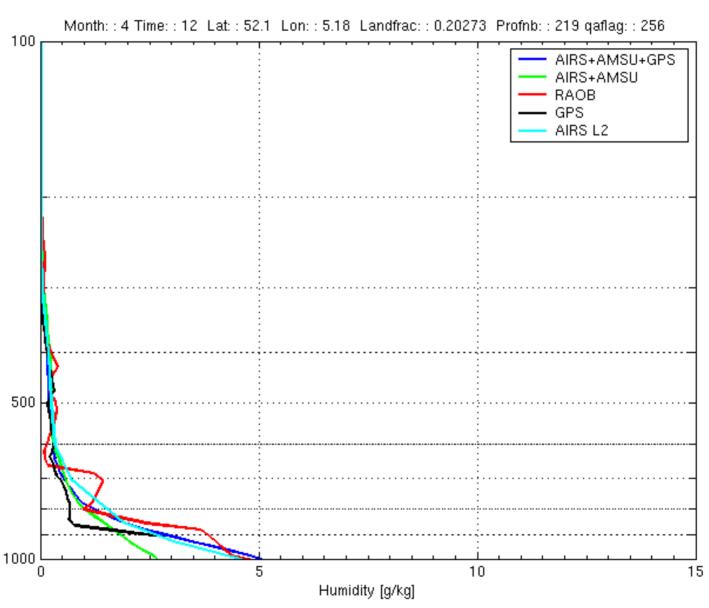
Comparison of temperature profiles







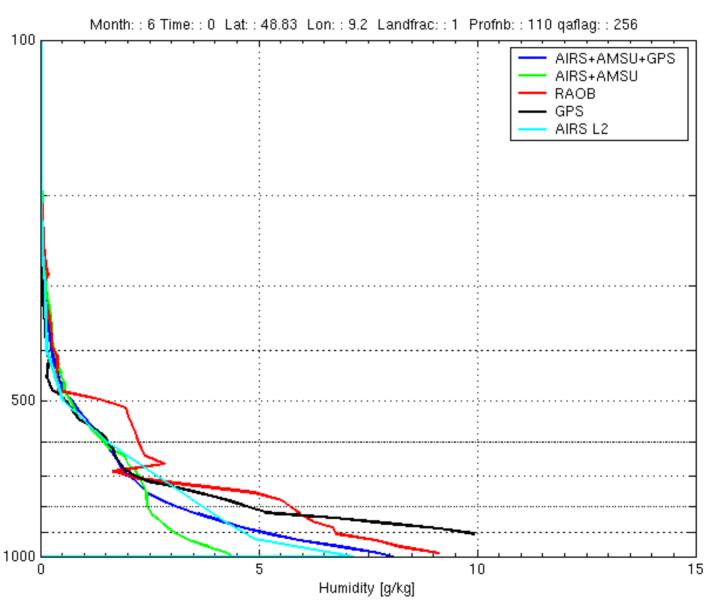
Comparison of moisture profiles







Comparison of moisture profiles







Conclusions

In clear sky conditions, AIRS L2 v3 temperature retrievals perform better than AIRS+AMSU regression retrievals but worse than AIRS+AMSU+GPS. The part of the atmosphere that shows the greatest improvement from inclusion of GPS is the tropopause.

For moisture, AIRS L2 is the best, followed by AIRS+AMSU+GPS and last is AIRS+AMSU (without GPS)

Future Plans

- Expand the dataset with more collocations
- Investigate the lower troposphere more
- Compare with operational AIRS L2 retrievals when v4 is available
- •Use v4 software to integrate GPS (if source code becomes available)
- Integrate GPS data in cloudy retrievals





