



Evaluation of sounding capability of the next generation Imager of Korea using the Advanced Himawari Imager data

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Introduction

- I6-channel Advanced Meteorological Imager (AMI) will be onboard next generation Geostationary Korea Multi-Purpose Satellite (GEO-KOMPSAT-2A) in 2018
- An iterative physical retrieval algorithm, based one dimensional variational (1DVAR) approach, has been developed to retrieve atmospheric temperature and moisture profiles from AMI
- the Unified Model (UM) 6-hour forecast fields with the spatial resolution of 25 km are utilized as the background profiles and the latest version of Radiative Transfer for TOVS (version RTTOV 11.2) is adopted for the calculation of the forward model.
- For the validation of the algorithm and for the investigation of feasibility of newly launched high performance imager data i.e., data from the Advanced Himawari Imager (AHI) on board Himawari-8, to the real time monitoring of severe weather phenomena, we applied the prototype algorithm to the AHI data.

Flowchart for the algorithm



- Algorithm AMI Atmospheric name: Profile (AAP) retrieval algorithm
- **Approach**: Iterative Optimal Estimation based 1DVAR (Li et al., 2012; EUMETSAT,

Results and Discussion

 Analysis of algorithm results (O-R) O-R by channel and by case (successful vs. fail / clear-sky vs. cloudy)

retrieval data: 20150614 00UTC





140.7E

- Products
 - Primary: Temperature(T)/moisture(q) profiles
 - Secondary: Total Precipitable Water, Atmospheric parameters (Lifted-index, K-index, Total Totals index, Showalter index, CAPE), and Total Column Ozone

Data and Methodology

• INPUT: AHI

- Data from AHI is used as a proxy to AMI

Comparisons of	the channels and resolutions of AHI and AMI	Channels used for AAP algorithm				
Platform /	IR channels	Spatial	Time resolution			

Sensor		8	9	10	11	12	13	14	15	16	Resolution	(full disk scan)
GK2A	AMI	6.24	6.95	7.34	8.60	9.63	10.4	11.2	12.3	13.3	2 km x 2 km	10 min.
Himawari	AHI	6.18	6.95	7.34	8.60	9.61	10.4	11.2	12.4	13.3	2 km x 2 km	10 min.

• First Guess for the algorithm: UM forecast fields

- UM 6hr forecast fields (Temperature, moisture, surface skin temperature)
- Radiative Transfer Model: RTTOV 11

- RTTOV v.11.2 is used for the calculation of the forward model and Jacobians

successful clear-sky	failed clear-sky	high clouds (no retrieval)
successful cloudy	failed cloudy	

	[Mean bias of O-R for Successful Retrievals] Ch 6.2 Ch 6.9 Ch 7.3 Ch 9.6 Ch 10.4 Ch 11.2 Ch 12.4 Ch 13.3											
case	Ch 6.2	Ch 6.9	Ch 7.3	Ch 9.6	Ch 10.4	Ch 11.2	Ch 12.4	Ch 13.3				
clear-sky	0.56	0.34	-0.07	-0.89	0.21	0.15	-0.17	-0.17				
cloudy	-0.72	-0.59	-1.60	-0.42	0.01	-0.92	-2.2	-2.62				

Comparison of difference between Observation and Background (O-B) vs Retrieval (O-R)

- The analysis is conducted for the 48 scenes between 0000 and 2300 UTC (with 30 minute interval) in June 14, 2015 within the ENH region.
- For each scene, about 84% of cloud-free observations succeed to retrieve profiles with the AAP algorithm
- Only the successfully retrieved, clear-sky pixels are analyzed to calculate O-B and O-R



- The latest version of RTTOV supports Himawari platform and AHI sensor
- 54 pressure levels (from 1050.0 to 0.005 hPa) are used

Surface Emissivity data

- Raw data: monthly Climatological data generated with CIMSS IREMIS (UW Baseline Fit Emissivity Database) (Seemann et al., 2007) is interpolated to AHI IR channels.
- * UW Baseline Fit Emissivity Database: global infrared land surface emissivity data available at ten wavelengths (3.6, 4.3, 5.0, 5.8, 7.6, 8.3, 9.3, 10.8, 12.1, and 14.3µm) with 0.05° x 0.05° spatial resolution
- Monthly climatological surface emissivity data is generated using the 12 years (2003-2014) CIMSS IREMIS database
- Channel interpolation: interpolated to 10 AHI infrared channels using Akima Spline method

IR Channels	3	4	5	6	7	8	9	10	11	12	13	14	15	μm
CIMSS IREMIS	3.	6, 4.3	s , 5.0 ,	5.8,	7.	6 , 8.	3, 9.3 ,	, 1	0.8,	12. 1	,	14	.3	
	📕 interpolate													
Himawari AHI	3	9 ,		6.2 ,	6.9,7	.3, 8	<mark>.6, 9.6</mark>	, 10.	<mark>4, 11.</mark>	2, 12.4	4, 13.	3		

- Match Coordinate: assign emissivity values to AHI grid points



: assign the nearest-point emissivity value to the AHI point

A1, A2, A3, A4: 4 surrounded latitude/longitude grids from the emissivity data (x,y) AHI latitude/longitude



Significant features

- As can be seen in the above mean O-B (1st column) and O-R (2nd column) images in 6.2, 6.9, 10.4 and 13.3 µm channels, O-R is smaller than O-B throughout the channels (red circles), although the investigation had been done for only one specific day.
- Significant improvement is found, particularly, in 10.4 channel, where the mean bias of O-R is about -0.08 K with RMSE 0.62 K, which is 24% smaller than that of O-B

Further study

- Sensitivity test of background error covariance matrix (UM vs. ECMWF) to algorithm performance
- Validation of the algorithm using radiosonde observations and UM analysis fields

References



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