

Optical Path Transmittance:
OPTRAN. Forward and Adjoint
Modeling

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Traditional Fast Transmittance Model

- Interpolate $T(P)$, $q(P)$ to fixed pressure levels
- Predictors T , q
- Include zenith angle as a predictor
- Predictand is transmittance departure or optical depth, multiple linear regression

Optical Path Transmittance (OPTRAN) approach

- Regression on levels of absorber amount
- Predictors are a function of T, P, q
- Zenith angle implicit in absorber amount
- Arbitrary pressure profile permitted
- Predictand is absorption coefficient for H₂O, O₃, mixed gases
- Permits changes to 'mixed gas' amounts as well

Heritage

- McMillin, Fleming and Hill (AO,1979)
- McMillin, Crone, Goldberg, Kleespies (AO,1995)
- McMillin, Crone, Kleespies (AO,1995)
- Three papers in the works

OPTRAN performance

- Water vapor channel much better than RTTOV
- Temperature channels generally not quite as good as RTTOV (before McMillin improvements)

What's this adjoint stuff it all about?

1DVAR / maximum probability solution is that which minimizes a 'cost' or 'penalty function:

$$\mathbf{J}(\mathbf{x}) = (\mathbf{x} - \mathbf{x}^b)^T \mathbf{B}^{-1} (\mathbf{x} - \mathbf{x}^b) + (\mathbf{y}^o - \mathbf{y}(\mathbf{x}))^T \mathbf{O}^{-1} (\mathbf{y}^o - \mathbf{y}(\mathbf{x}))$$

where \mathbf{x}^b is an initial estimate given by the model state vector, \mathbf{x} is the model state for which the solution is desired, \mathbf{y}^o is the vector of observations, $\mathbf{y}(\mathbf{x})$ is an operator which transforms the model state vector into the same parameters as the observations, and \mathbf{B} and \mathbf{O} are the background and observational error covariance matrices respectively. For our purposes, $\mathbf{y}(\mathbf{x})$ is the radiative transfer operator. Note that \mathbf{O} is a combination of observational errors and radiative transfer errors. (This is just a least squares problem)

What's it all about: part deux

How do we find the minimum? From first quarter Calculus:
Take the first derivative and set it equal to zero.

$$\nabla \mathbf{J}(\mathbf{x}) = \mathbf{B}^{-1} (\mathbf{x} - \mathbf{x}^b) - \mathbf{K}(\mathbf{x})^T \mathbf{O}^{-1} (\mathbf{y}^o - \mathbf{y}(\mathbf{x})) = 0$$

where $\mathbf{K}(\mathbf{x})$ is the matrix of partial derivatives of $\mathbf{y}(\mathbf{x})$ with respect to the elements of \mathbf{x} . (factor of 2 divides out)

What's it all about: part trois

It is evident that the solution requires both the forward radiative transfer operator $\mathbf{y}(\mathbf{x})$, and the transpose of its derivative, $\mathbf{K}(\mathbf{x})^T$. $\mathbf{K}(\mathbf{x})^T$ is called the adjoint, or Jacobian.

$$\mathbf{x} = \{ \mathbf{T}_1, \mathbf{T}_2, \mathbf{T}_3, \dots, \mathbf{T}_n, \mathbf{q}_1, \mathbf{q}_2, \mathbf{q}_3, \dots, \mathbf{q}_n, \dots \}$$

$$\mathbf{y}(\mathbf{x}) = \{ \mathbf{R}_1, \mathbf{R}_2, \mathbf{R}_3, \dots, \mathbf{R}_m \}^T$$

What's it all about, part quatre

$$\mathbf{K}(\mathbf{x})^T = \begin{bmatrix} \frac{\partial \mathbf{R}_1}{\partial \mathbf{T}_1} & \frac{\partial \mathbf{R}_2}{\partial \mathbf{T}_1} & \frac{\partial \mathbf{R}_3}{\partial \mathbf{T}_1} & \dots & \frac{\partial \mathbf{R}_m}{\partial \mathbf{T}_1} \\ \frac{\partial \mathbf{R}_1}{\partial \mathbf{T}_2} & \frac{\partial \mathbf{R}_2}{\partial \mathbf{T}_2} & \frac{\partial \mathbf{R}_3}{\partial \mathbf{T}_2} & \dots & \frac{\partial \mathbf{R}_m}{\partial \mathbf{T}_2} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ \frac{\partial \mathbf{R}_1}{\partial \mathbf{T}_n} & \frac{\partial \mathbf{R}_2}{\partial \mathbf{T}_n} & \frac{\partial \mathbf{R}_3}{\partial \mathbf{T}_n} & \dots & \frac{\partial \mathbf{R}_m}{\partial \mathbf{T}_n} \\ \frac{\partial \mathbf{R}_1}{\partial \mathbf{q}_1} & \frac{\partial \mathbf{R}_2}{\partial \mathbf{q}_1} & \frac{\partial \mathbf{R}_3}{\partial \mathbf{q}_1} & \dots & \frac{\partial \mathbf{R}_m}{\partial \mathbf{q}_1} \\ \frac{\partial \mathbf{R}_1}{\partial \mathbf{q}_2} & \frac{\partial \mathbf{R}_2}{\partial \mathbf{q}_2} & \frac{\partial \mathbf{R}_3}{\partial \mathbf{q}_2} & \dots & \frac{\partial \mathbf{R}_m}{\partial \mathbf{q}_2} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ \frac{\partial \mathbf{R}_1}{\partial \mathbf{q}_n} & \frac{\partial \mathbf{R}_2}{\partial \mathbf{q}_n} & \frac{\partial \mathbf{R}_3}{\partial \mathbf{q}_n} & \dots & \frac{\partial \mathbf{R}_m}{\partial \mathbf{q}_n} \end{bmatrix}$$

What's it all about, part cinq

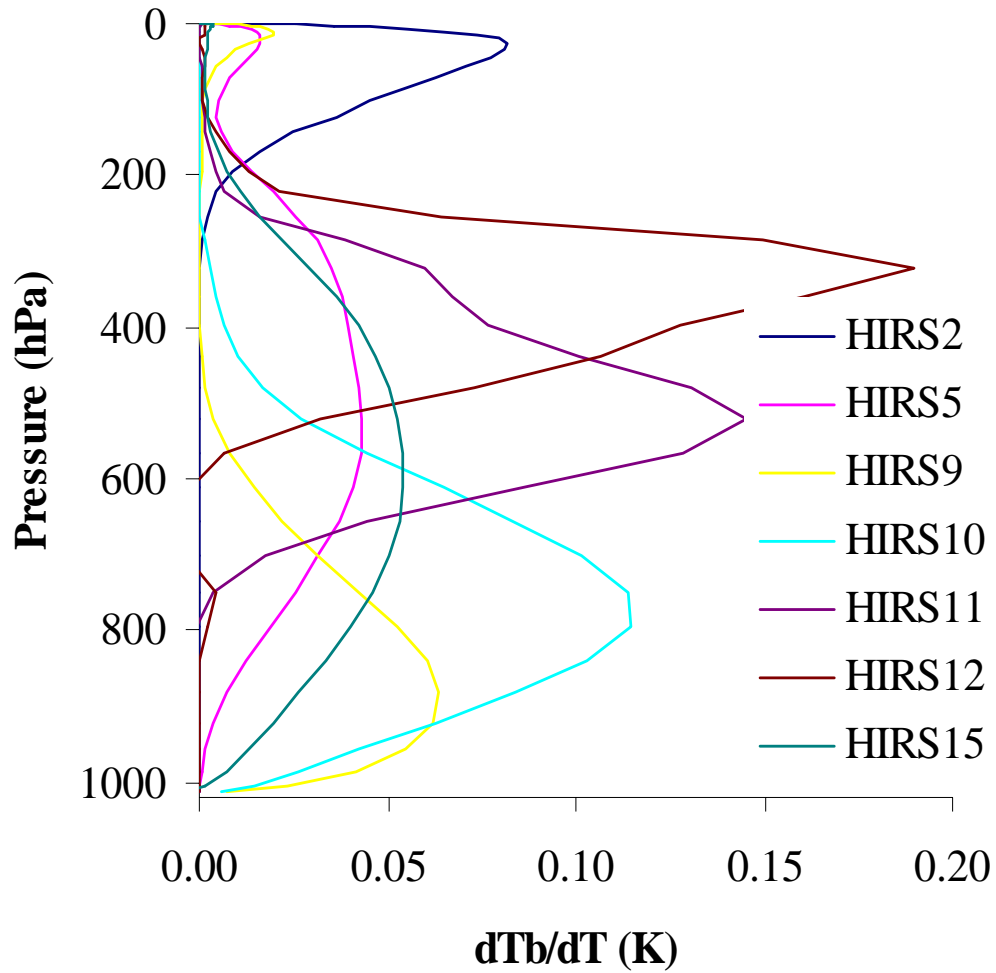
In olden days (say 1990), computation of $\mathbf{K}(\mathbf{x})^T$ required $N+1$ forward model calculations using forward (or backward) finite differencing (centered required $2N+1$). Thus these techniques were only used in limited studies

In these modern times, using adjoint coding techniques $\mathbf{K}(\mathbf{x})^T$ can be computed with the effort of about 3 forward model calculations.

What are these all the models?

- The **tangent linear** model is derived from the forward model
 - gives the derivative of the radiance with respect to the state vector (vector output, m channels)
- The **adjoint** is derived from the tangent linear model
 - gives the transpose of the derivative of the radiance with respect to the state vector (vector output, N variables)
- The **Jacobian** is derived from the adjoint model
 - gives the transpose of the derivative of the radiance with respect to the state vector by channel (matrix output, $N \times m$)
- At NCEP, only the forward and the Jacobian models are actually used, but all models must be developed and maintained in order to assure a testing path, and to make sure the performance is correct.

Tropical Temperature derivatives for NOAA 14



Why can't we just use the Tangent Linear Model?

- You can.
- However, it still takes N TL calculations.
- You avoid the finite differencing because the TL is the analytic derivative, but you just get a vector of radiances for each call. You still have to call it for each element of the input vector.

Testing

- Testing the code is rigorous and analytic
- Each code is tested for consistency with the model from which it was developed
- Code is tested bottom up, lowest level first.
- Full TL model is tested before moving to adjoint
- Full Adjoint is tested before moving to Jacobian

Adjoint Compiler

- Giering and others have written compilers that generate TL and adjoint code
- Some people at NCAR swear by them
- Others swear at them (just kidding)
- We feel that better optimization can be achieved by hand coding.

Summary

- Quick overview of OPTRAN
- Description of Adjoint and associated models
- Keep these brave souls who will take the coding class in your thoughts.

Class Participants Please Remain
for a Few Minutes